

Example 174/P.247

We know, $a = \frac{dv}{dt}$

$$\Rightarrow dv = a dt$$

$$\Rightarrow \int dv = \int a dt$$
$$= \int 4t dt$$

$$\therefore v = 4 \cdot \frac{t^2}{2} + C$$
$$= 2t^2 + C \quad \text{--- (i)}$$

Given, At $t=0$, $v = 10$ fps

Substituting in eqⁿ (i)

$$10 = 0 + C$$

$$\Rightarrow C = 10$$

Therefore, the eqⁿ for velocity is

$$v = 2t^2 + 10 \quad \text{--- (ii)}$$

at $t=4$ sec, $v = 2 \cdot 4^2 + 10 = \boxed{42 \text{ fps}}$ Ans.

Again $v = \frac{ds}{dt} \Rightarrow ds = v dt$

$$\int ds = \int v dt$$
$$= \int (2t^2 + 10) dt$$

$$\therefore s = 2 \cdot \frac{t^3}{3} + 10t + C_1$$

at $t=0$, $s=0 \Rightarrow C_1=0$

$$\therefore s = \frac{2}{3}t^3 + 10t$$

Now, at $t=4$ sec.

$$s = \frac{2}{3} \times 4^3 + 10 \times 4 = \boxed{82.7 \text{ ft}}$$
 Ans.

Note: Definite Integral has been used in the book; an alternative way.

Ex. 186/P. 258

(a)

$\omega_0 = 0$, counterclock rotation

$$\theta = 0.1t^3 - 0.3t^2 + 0.8t$$

$$t = 6 \text{ s.}$$

(a) $\theta_6 = ?$ (b) $\omega_6 = ?$ (c) $\alpha_6 = ?$

Solⁿ

$$(a) \theta_6 = 0.1 \times 6^3 - 0.3 \times 6^2 + 0.8 \times 6 = \boxed{15.6 \text{ s.}}$$

$$(b) \omega = \frac{d\theta}{dt} = \frac{d}{dt} (0.1t^3 - 0.3t^2 + 0.8t) = 0.3t^2 - 0.6t + 0.8$$

$$\therefore \omega_6 = 0.3 \times 6^2 - 0.6 \times 6 + 0.8 = \boxed{8 \text{ rad/s.}}$$

$$(c) \alpha = \frac{d\omega}{dt} = \frac{d}{dt} (0.3t^2 - 0.6t + 0.8) = 0.6t - 0.6$$

$$\therefore \alpha_6 = 0.6 \times 6 - 0.6 = \boxed{3 \text{ rad/s}^2}$$

Ex. 188/PP. 259-261

Given, $\omega_0 = 300 \text{ rpm} = \frac{300 \times 2\pi}{60} \text{ rad/s} = 31.4 \text{ rad/s}$.

$$\alpha = -2 \text{ rad/s}^2$$

(a) $t = ?$ for $\omega = 0$

(b) $\omega = ?$ for $t = 10 \text{ s}$.

(c) No. of revolutions in first 10 s. i.e. $\theta = ?$

(d) $\theta = ?$ to stop i.e. $\omega = 0$

(e) No. of revolutions from $t = 10 \text{ s}$. to $\omega = 0$

Solⁿ

(a) $\omega = \omega_0 + \alpha t$

$$\Rightarrow 0 = 31.4 - 2 \times t$$

$$\therefore t = \boxed{15.7 \text{ s.}}$$

(b) $\omega = \omega_0 + \alpha t$

$$= 31.4 - 2 \times 10$$

$$= 11.4 \text{ rad/s.}$$

$$= \frac{11.4 \times 60}{2\pi} \text{ rpm}$$

$$\approx \boxed{109 \text{ rpm}}$$

(c) $\theta = \omega_0 t + \frac{1}{2} \alpha t^2$

$$= 31.4 \times 10 + \frac{1}{2} \times (-2) \times 10^2$$

$$= 214 \text{ rad}$$

$$= \frac{214}{2\pi} \text{ rev.}$$

$$= \boxed{34.06 \text{ rev.}}$$

(d) $\omega^2 = \omega_0^2 + 2\alpha\theta$

$$\Rightarrow 0 = (31.4)^2 + 2(-2) \cdot \theta$$

$$\therefore \theta = \boxed{246.49 \text{ rad.}}$$

(e) from (d) \rightarrow to stop, $\theta = 246.49 \text{ rad}$

from (c) \rightarrow at $t = 10 \text{ s}$, $\theta = 214 \text{ rad}$

$$\therefore \text{From } t = 10 \text{ s. to stop, } \theta = 246.49 - 214$$

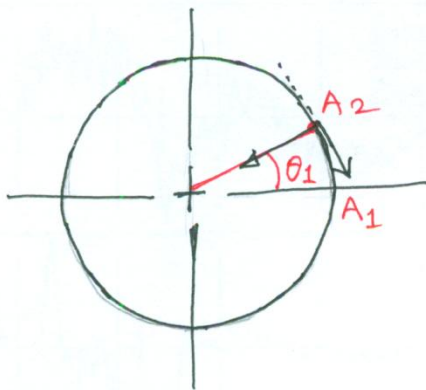
$$= 32.49 \text{ rad}$$

$$= \frac{32.49}{2\pi} \text{ rev.}$$

$$= \boxed{5.2 \text{ rev.}}$$

#325'

Ex. 191 / pp. 203-204



Total acclⁿ of a point, that was initially at A_1 , after 10 s. = ?

A_2 ← position of the point after 10 s.

from ex. 188(c), for $t = 10$ s.

$$\theta = 214 \text{ rad} = 34.06 \text{ rev.}$$

$$\therefore \theta_1 = 0.06 \times 360^\circ = 21.6^\circ$$

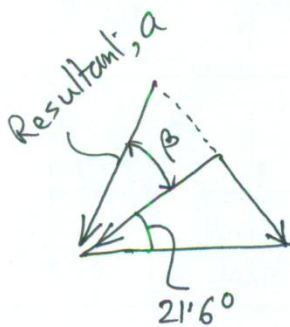
$$r = \frac{30''}{2} = 1.25 \text{ ft}$$

$$\therefore a_t = r\alpha = 1.25 \times 2 = 2.5 \text{ fps}^2 \text{ (clockwise)}$$

$$a_n = \frac{v^2}{r} = r\omega^2 = v\omega$$

from ex. 118(b), $\omega = 11.4 \text{ rad/s}$.

$$\therefore a_n = r\omega^2 = 1.25 \times 11.4^2 = 162.45 \text{ fps}^2 \text{ (towards center)}$$



$$\text{Resultant accl}^n, a = \sqrt{a_t^2 + a_n^2}$$

$$= \sqrt{2.5^2 + 162.45^2}$$

$$= \boxed{162.5 \text{ fps}^2}$$

$$\beta = \tan^{-1} \frac{a_t}{a_n} = \tan^{-1} \frac{2.5}{162.45} = 0.88^\circ$$

\therefore Direction of total acclⁿ with

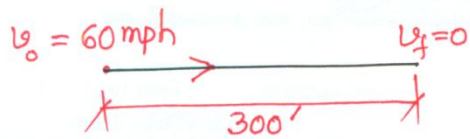
$$\text{horizontal} = \theta_1 + \beta$$

$$= 21.6 + 0.88$$

$$= \boxed{22.48^\circ}$$

896/P. 275

situation 1 / Test



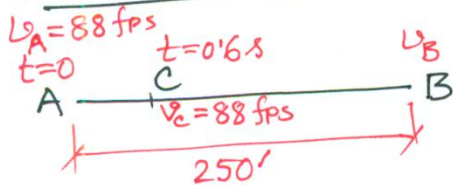
$$60 \text{ mph} = \frac{60 \times 1760 \times 3}{60 \times 60} \text{ fps}$$
$$= 88 \text{ fps}$$

$$u_f^2 = u_0^2 + 2as$$

$$\Rightarrow 0 = 88^2 + 2 \times a \times 300$$

$$\therefore a = -12.91 \text{ fps}^2$$

situation 2



$$AC = u_A t$$
$$= 88 \times 0.6$$
$$= 52.8 \text{ ft}$$

$$CB = AB - AC = 250 - 52.8 = 197.2 \text{ ft}$$

For motion from C to B

$$u_B^2 = u_C^2 + 2a \cdot s_{CB}$$

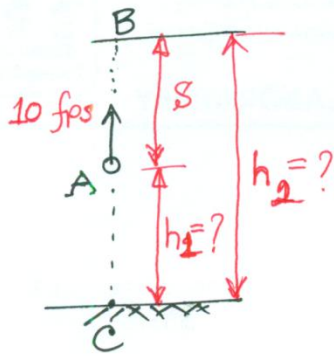
$$= 88^2 + 2 \times (-12.91) \times 197.2$$

$$\therefore u_B = \boxed{51.5 \text{ fps}} \text{ Ans.}$$

$$= 51.5 \times 60 \text{ fpm} = \boxed{3090 \text{ fpm}} \text{ Ans.}$$

$$= \frac{51.5 \times 60 \times 60}{1760 \times 3} \text{ mph} = \boxed{35.1 \text{ mph}} \text{ Ans.}$$

901 / P. 276



For both balloon & sandbag,

$$v_0 = -10 \text{ fps (downward +ve)}$$

For the upward motion of the sandbag upto max^m altitude

$$v_f = v_0 + gt_1$$

$$\Rightarrow 0 = -10 + 32.2 \times t_1$$

$$\therefore t_1 = \frac{10}{32.2} = 0.31 \text{ s.}$$

$$s = v_0 t_1 + \frac{1}{2} g t_1^2$$

$$= -10 \times 0.31 + \frac{1}{2} \times 32.2 \times 0.31^2$$

$$= -1.55 \text{ ft (-ve sign implies upward displacement)}$$

For the sandbag to drop from the max^m altitude to ground

$$t_2 = 4 - 0.31 = 3.69 \text{ s.}$$

$$h_2 = \frac{1}{2} g t_2^2 = \frac{1}{2} \times 32.2 \times 3.69^2 = \boxed{219.22 \text{ ft}} \text{ Ans.}$$

$$h_1 = h_2 - s = 219.22 - 1.55 = \boxed{217.67 \text{ ft.}} \text{ Ans.}$$

Alternatively

Considering motion A \rightarrow C }
$$h_1 = v_0 t + \frac{1}{2} g t^2 = -10 \times 4 + \frac{1}{2} \times 32.2 \times 4^2 = \boxed{217.67 \text{ ft.}} \text{ Ans.}$$

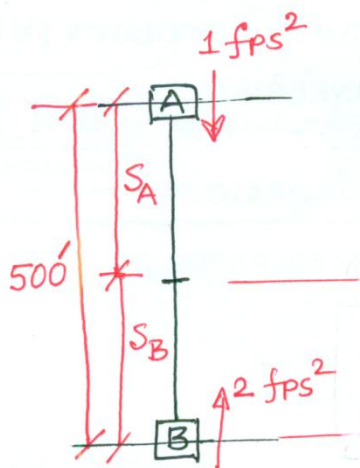
$$A \rightarrow B \quad v_f^2 = v_0^2 + 2gS$$

$$\Rightarrow 0 = (-10)^2 + 2 \times 32.2 \times S$$

$$\therefore S = \boxed{-1.55 \text{ ft}}$$

$$\therefore h_2 = h_1 + S = 217.67 + 1.55 = \boxed{219.22 \text{ ft.}} \text{ Ans}$$

903/P. 276



Given :

A & B start simultaneously

$$v_A = 0, v_B = 0$$

$$a_A = 1 \text{ fps}^2 \downarrow$$

$$a_B = 2 \text{ fps}^2 \uparrow$$

$$S_A = ? \quad S_B = ?$$

Solⁿ

Let the two elevators be opposite to each other after t sec. ~~and by this time elev. B travels a distance x~~

Let's take downward directⁿ as +ve

$$\begin{aligned} \text{For motion of elev. A, } S_A &= \frac{1}{2} a_A t^2 \\ &= \frac{1}{2} \times 1 \times t^2 \\ &= 0.5 t^2 \end{aligned}$$

$$\begin{aligned} \text{For motion of elev. B, } -S_B &= \frac{1}{2} a_B t^2 \\ \Rightarrow -S_B &= \frac{1}{2} \times (-2) t^2 \\ \therefore S_B &= t^2 \end{aligned}$$

$$\text{Now } S_A + S_B = 500$$

$$\Rightarrow 0.5 t^2 + t^2 = 500$$

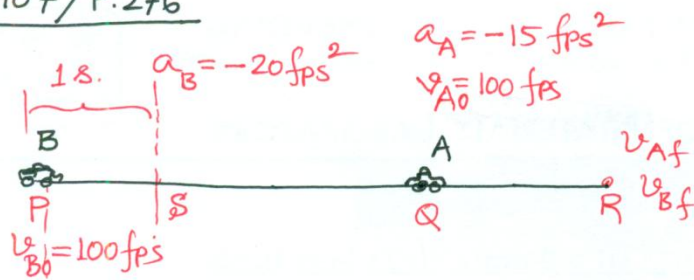
$$\Rightarrow 1.5 t^2 = 500$$

$$\therefore t = 18.26 \text{ s}$$

$$\therefore S_A = 0.5 \times 18.26^2 = \boxed{166.7 \text{ ft}} \text{ Ans.}$$

$$\& S_B = 18.26^2 = \boxed{333.4 \text{ ft.}} \text{ Ans.}$$

907/P.276



For bumper to bumper touch

$$SPQ = ?$$

$$t = ?$$

$$v_{Af} = ?$$

$$v_{Bf} = ?$$

Let the points P & Q in the above figure be the initial positions of the automobiles A & B respectively and let R_S be the point where B's brake is applied.

For vehicle A (motion from Q to R)

$$v_{Af} = v_{A0} + a_A t = 100 + (-15)t = 100 - 15t \quad \text{--- ①}$$

For vehicle B (motion from S to R)

$$v_{Bf} = v_{B0} + a_B (t-1) = 100 + (-20)(t-1) = 120 - 20t \quad \text{--- ②}$$

For bumper-to-bumper condition to occur

$$v_{Af} = v_{Bf}$$

$$\Rightarrow 100 - 15t = 120 - 20t$$

$$\Rightarrow 5t = 20$$

$$\therefore t = \boxed{4 \text{ sec.}} \text{ Ans.}$$

$$\therefore \text{from eqn ①, } \boxed{v_{Af} = 100 - 15 \times 4 = 40 \text{ fps} = v_{Bf}} \text{ Ans.}$$

Again for vehicle A

$$S_{QR} = v_{A0} t + \frac{1}{2} a_A t^2 = 100 \times 4 + \frac{1}{2} \times (-15) \times 4^2 = 280 \text{ ft}$$

and for vehicle B

$$S_{SR} = v_{B0} (t-1) + \frac{1}{2} a_B (t-1)^2 = 100 \times (4-1) + \frac{1}{2} \times (-20) \times (4-1)^2 = 210 \text{ ft}$$

$$\begin{aligned} \therefore \text{Required distance, } S_{PQ} &= S_{PS} + (S_{SR} - S_{QR}) \\ &= 100 \times 1 + (210 - 280) \\ &= \boxed{30 \text{ ft}} \text{ Ans.} \end{aligned}$$

#916/P.276

$$a = 5t^{1/3}$$

at $t=0$, $v_0 = 6$ fps and $s_0 = 0$

$s = ?$ betwⁿ $t = 4$ s. and $t = 10$ s.

Solⁿ

$$a = \frac{dv}{dt}$$

$$\Rightarrow dv = a dt$$

$$\Rightarrow \int_{v_0}^{v_f} dv = \int_0^t 5t^{1/3} dt$$

$$\Rightarrow v_f - v_0 = 5 \times \frac{3}{4} t^{4/3}$$

$$\therefore v = \frac{15}{4} t^{4/3} + 6$$

Again $v = \frac{ds}{dt}$

$$\Rightarrow ds = v dt$$

$$\Rightarrow \int_0^s ds = \int_4^{10} \left(\frac{15}{4} t^{4/3} + 6 \right) dt$$

$$\therefore s = \frac{15}{4} \times \frac{3}{7} \left[t^{7/3} \right]_4^{10} + 6 \left[t \right]_4^{10}$$

$$= 305.42 + 36$$

$$= \boxed{341.42 \text{ ft}}$$

Ans.

921/P.277

$$s = (t^2 - 2t + 9)^{1/2} \text{ ft; } t \text{ in sec.}$$

$$v_3 = ? \quad a_3 = ? \quad \text{at } t = 3 \text{ s.}$$

$$\text{Avg. accel}^n \text{ in 3rd sec.} = ?$$

$$v = \frac{ds}{dt} = \frac{dt}{dt} (t^2 - 2t + 9)^{1/2} = \frac{1}{2} (t^2 - 2t + 9)^{-1/2} \cdot (2t - 2) = \frac{t-1}{(t^2 - 2t + 9)^{1/2}}$$

$$a = \frac{dv}{dt}$$

$$= \frac{d}{dt} \left[\frac{t-1}{(t^2 - 2t + 9)^{1/2}} \right]$$

$$= \frac{(t^2 - 2t + 9)^{1/2} \cdot 1 - (t-1) \cdot \frac{1}{2} (t^2 - 2t + 9)^{-1/2} \cdot (2t-2)}{(t^2 - 2t + 9)^2}$$

$$= \frac{(t^2 - 2t + 9)^{1/2} - (t-1)^2 (t^2 - 2t + 9)^{-1/2}}{t^2 - 2t + 9}$$

$$= (t^2 - 2t + 9)^{-1/2} - (t-1)^2 (t^2 - 2t + 9)^{-3/2}$$

at $t = 3 \text{ sec.}$

$$v = \frac{3-1}{(3^2 - 2 \times 3 + 9)^{1/2}} = \boxed{0.577 \text{ fps}} \text{ Ans.}$$

$$a = (3^2 - 2 \times 3 + 9)^{-1/2} - (3-1)^2 (3^2 - 2 \times 3 + 9)^{-3/2} = \boxed{0.192 \text{ fps}^2} \text{ Ans.}$$

at $t = 2 \text{ sec.}$

$$a = (2^2 - 2 \times 2 + 9)^{-1/2} - (2-1)^2 (2^2 - 2 \times 2 + 9)^{-3/2} = 0.296 \text{ fps}^2$$

\therefore Arithmetic avg. accelⁿ during the 3rd second

$$= \frac{0.296 + 0.192}{2}$$

$$= \boxed{0.244 \text{ fps}^2} \text{ Ans.}$$

922 / P. 277

$$a = 3t - 12 \text{ fps}^2$$

at $t=0$, $\frac{v_0}{a} = 15 \text{ fps}^2$ in the same sense as initial accelⁿ

$v = ?$ and $s = ?$ at $t = 3 \text{ s}$.

Solⁿ

$$\text{at } t=0, a = -12 \text{ fps}^2$$

$$\therefore v_0 = -15 \text{ fps}$$

$$\text{Now } a = \frac{dv}{dt}$$

$$\Rightarrow dv = a dt$$

$$\Rightarrow \int_{-15}^v dv = \int_0^t (3t - 12) dt$$

$$\Rightarrow v + 15 = \frac{3}{2}t^2 - 12t$$

$$\therefore v = \frac{3}{2}t^2 - 12t - 15$$

$$\text{at } t = 3 \text{ s}, v = \frac{3}{2} \times 3^2 - 12 \times 3 - 15 = -37.5 \text{ fps}$$

-ve sign implies that directⁿ of velocity is same as that of initial accelⁿ.

Ans.

$$\text{Again } v = \frac{ds}{dt}$$

$$\Rightarrow ds = v dt = \left(\frac{3}{2}t^2 - 12t - 15 \right) dt$$

$$\Rightarrow \int_0^s ds = \int_0^t \left(\frac{3}{2}t^2 - 12t - 15 \right) dt$$

$$\therefore s = \frac{1}{2}t^3 - 6t^2 - 15t$$

$$\text{at } t = 3 \text{ s}, s = \frac{1}{2} \times 3^3 - 6 \times 3^2 - 15 \times 3 = -85.5 \text{ ft}$$

-ve sign means opposite to the +ve coordinate directⁿ

Ans.

939/P.278

$$\text{Here, } \omega_0 = 1200 \text{ rpm} = \frac{1200}{60} \times 2\pi = 40\pi \text{ rad/s}$$

$$\omega_f = 0, \quad \alpha = 100 \text{ rpm}^2$$

(a) no. of revolution = ?

$$t = ?$$

(b) $\omega_f = 300 \text{ rpm}$, $\omega_0 = 1200 \text{ rpm}$

$$\theta = 7500 \text{ rev.}$$

$$\alpha = ? \text{ in rad/s}^2$$

Solⁿ

(a) $\omega_f = \omega_0 - \alpha t$

$$\Rightarrow 0 = 1200 - 100t$$

$$\therefore t = \frac{1200}{100} = 12 \text{ min}$$

$$\theta = \omega_0 t - \frac{1}{2} \alpha t^2$$

$$= 1200 \times 12 - \frac{1}{2} \times 100 \times 12^2$$

$$= 7200 \text{ rev.}$$

(b) $\omega_f^2 = \omega_0^2 - 2\alpha\theta$

$$\Rightarrow 300^2 = 1200^2 - 2\alpha \times 7500$$

$$\therefore \alpha = \frac{1}{2 \times 7500} (1200^2 - 300^2)$$

$$= 90 \text{ rpm}^2$$

$$= \frac{90 \times 2\pi}{60 \times 60} \text{ rad/s}^2$$

$$= 0.157 \text{ rad/s}^2$$

943/P.279

$$\theta = t - 0.1t^2 \text{ rad, } t \text{ in sec.}$$

$$\left. \begin{array}{l} \text{(a) } \theta = ? \\ \omega = ? \\ \alpha = ? \end{array} \right\} \text{ after } t = 3 \text{ sec.}$$

(b) same as (a) after 10 sec

(c) Max^m displacement during the first 10 sec.

Solⁿ

$$\text{(a) } \theta = t - 0.1t^2$$

$$\therefore \text{ after 3 sec. } \theta = 3 - 0.1 \times 3^2 = \boxed{2.1 \text{ rad}} \text{ Ans.}$$

$$\omega = \frac{d\theta}{dt} = 1 - 0.2t$$

$$\therefore \omega_{3 \text{ sec.}} = 1 - 0.2 \times 3 = \boxed{0.4 \text{ rad/s}} \text{ Ans.}$$

$$\alpha = \frac{d\omega}{dt} = \boxed{-0.2 \text{ rad/s}^2} \text{ Ans.}$$

$$\text{(b) after 10 sec, } \theta = 10 - 0.1 \times 10^2 = \boxed{0 \text{ rad}} \text{ Ans.}$$

$$\omega = 1 - 0.2 \times 10 = \boxed{-1 \text{ rad/s}} \text{ Ans.}$$

$$\alpha = \boxed{-0.2 \text{ rad/s}^2} \text{ Ans.}$$

(c) for maximum displacement

$$\frac{d\theta}{dt} = 0$$

$$\Rightarrow 1 - 0.2t = 0$$

$$\therefore t = \frac{1}{0.2} = 5 \text{ s}$$

$$\therefore \theta_{\text{max}} = 5 - 0.1 \times 5^2 = \boxed{2.5 \text{ rad}} \text{ Ans.}$$

948/P.279

$$\alpha = 2\theta$$

at $t=0$, $\omega = \omega_0$ and $\theta = 0$

Find the general expression for ω .

Solⁿ

we know $\alpha d\theta = \omega d\omega$

$$\Rightarrow 2\theta d\theta = \omega d\omega$$

$$\Rightarrow 2 \int_{\theta=0}^{\theta} \theta d\theta = \int_{\omega_0}^{\omega} \omega d\omega$$

$$\Rightarrow [\theta^2]_0^{\theta} = \frac{1}{2} [\omega^2]_{\omega_0}^{\omega}$$

$$\Rightarrow \theta^2 = \frac{1}{2} (\omega^2 - \omega_0^2)$$

$$\Rightarrow \omega^2 = \omega_0^2 + 2\theta^2$$

$$\therefore \omega = \pm (\omega_0^2 + 2\theta^2)^{1/2}$$

958/P.280

Here, $v_A = \text{Const.} = 10 \text{ fps} \downarrow$

(a) $\omega_P = ?$ and $v_P = ?$ at $t = 3 \text{ s.}$

(b) $a_{np} = ?$ and $a_{tp} = ?$

Solution

(a) $v_B = v_A = 10 \text{ fps}$

$$v_B = r_B \omega$$

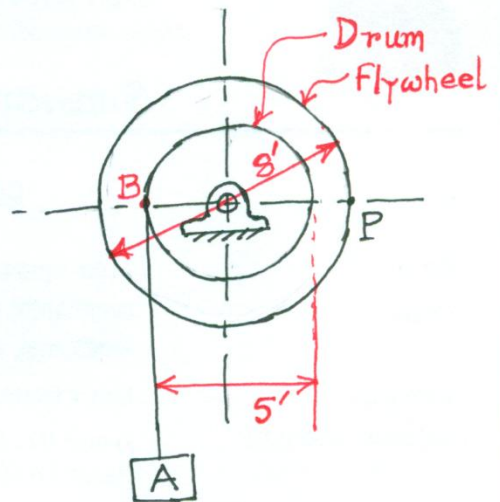
$$v_P = r_P \omega$$

$$\therefore \frac{v_P}{v_B} = \frac{r_P}{r_B} \Rightarrow v_P = \frac{r_P}{r_B} \cdot v_B = \frac{4}{2.5} \times 10 = \boxed{16 \text{ fps}}$$

$$\omega = \omega_P = \frac{v_P}{r_P} = \frac{16}{4} = \boxed{4 \text{ rad/s}}$$

(b) $a_{np} = r_P \omega_P^2 = 4 \times 4^2 = \boxed{64 \text{ fps}^2}$

$$a_{tp} = r_P \alpha_P = r_P \cdot \frac{d\omega_P}{dt} = \boxed{0} \quad \left[\text{Because } \omega_P = \text{Constant} \right]$$

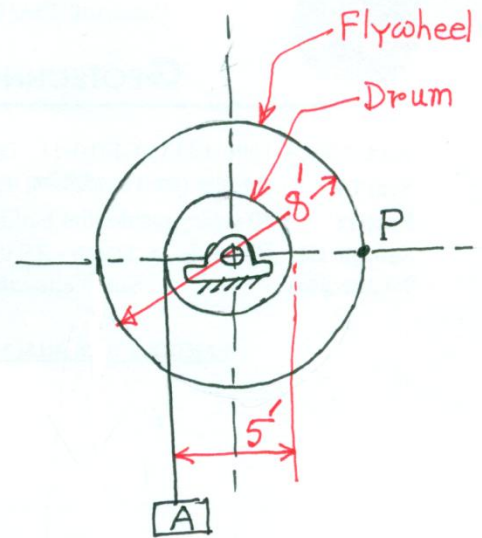


960/P. 280

$$a_A = \frac{g}{2} - \frac{t}{12}$$

$$v_0 = 10 \text{ fps}$$

$$\left. \begin{array}{l} \text{(a) } \omega_{P3} = ? \quad v_{P3} = ? \\ \text{(b) } a_{nP3} = ? \quad a_{tP3} = ? \end{array} \right\} \begin{array}{l} \text{when} \\ t = 3 \text{ sec.} \end{array}$$



Solⁿ

$$dv_A = a_A dt$$

$$\Rightarrow \int_{v_0}^{v_{At}} dv_A = \int_0^t \left(\frac{g}{2} - \frac{t}{12} \right) dt$$

$$\Rightarrow \left[v_A \right]_{v_0}^{v_{At}} = \left[\frac{gt}{2} - \frac{t^2}{24} \right]_0^t$$

$$\Rightarrow v_{At} - v_0 = \frac{gt}{2} - \frac{t^2}{24}$$

$$\therefore v_{At} = v_0 + \frac{gt}{2} - \frac{t^2}{24} = 10 + \frac{gt}{2} - \frac{t^2}{24} \quad \text{--- (1)}$$

$$\text{at } t = 3 \text{ s.}, v_{A3} = 10 + \frac{32.2 \times 3}{2} - \frac{3^2}{24} = 57.93 \text{ fps.}$$

$$\omega_{P3} = \frac{v_{A3}}{r_A} = \frac{57.93}{2.5} = \boxed{23.17 \text{ rad/s}} \text{ Ans.}$$

$$v_{P3} = r_P \omega_{P3} = 4 \times 23.17 = \boxed{92.68 \text{ fps}} \text{ Ans.}$$

$$a_{nP3} = r_P \omega_{P3}^2 = 4 \times \frac{23.17^2}{2.5} = \boxed{2147.40 \text{ fps}^2} \text{ Ans.}$$

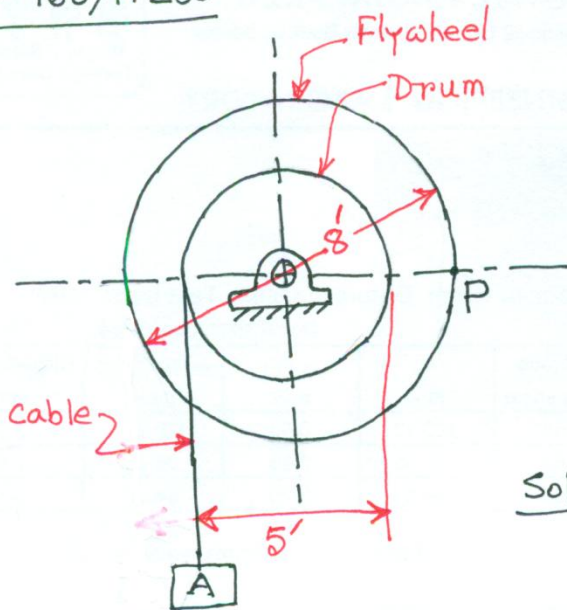
$$a_{tP3} = r_P \alpha_{P3}$$

$$\alpha_{Pt} = \frac{d\omega_{Pt}}{dt} = \frac{d}{dt} \left[\frac{v_{At}}{r_A} \right] = \frac{d}{dt} \left[\frac{v_{At}}{r_A} \right] = \frac{1}{r_A} \frac{d}{dt} \left(10 + \frac{gt}{2} - \frac{t^2}{24} \right)$$

$$\therefore \alpha_{P3} = \frac{1}{2.5} \left(\frac{32.2}{2} - \frac{3}{12} \right) = 6.34 \text{ rad/s}^2 = \frac{1}{r_A} \times \left(\frac{g}{2} - \frac{t}{12} \right)$$

$$\therefore a_{tP3} = r_P \cdot \alpha_{P3} = 4 \times 6.34 = \boxed{25.36 \text{ fps}^2} \text{ Ans.}$$

960/P.280



$$a_A = \frac{g}{2} - \frac{t}{12}$$

$$v_0 = 10 \text{ fps}$$

Determine:

$$\left. \begin{array}{l} \text{(a) } \omega_{P3} = ? \quad v_{P3} = ? \\ \text{(b) } a_{nP3} = ? \quad a_{tP3} = ? \end{array} \right\} \text{ when } t = 3 \text{ s.}$$

Solution

$$dv_A = a_A dt$$

$$\Rightarrow \int_{v_0}^{v_{At}} dv_A = \int_0^t \left(\frac{g}{2} - \frac{t}{12} \right) dt$$

$$\Rightarrow [v_A]_{v_0}^{v_{At}} = \left[\frac{gt}{2} - \frac{t^2}{24} \right]_0^t$$

$$\Rightarrow v_{At} - v_0 = \frac{gt}{2} - \frac{t^2}{24}$$

$$\therefore v_{At} = v_0 + \frac{gt}{2} - \frac{t^2}{24}$$

$$= 10 + \frac{gt}{2} - \frac{t^2}{24} \quad \text{--- (1)}$$

$$\omega_{Pt} = \omega_{At} = \frac{v_{At}}{r_A} = \frac{1}{2.5} \left(10 + \frac{gt}{2} - \frac{t^2}{24} \right) \quad \text{--- (2)}$$

$$\therefore \omega_{P3} = \frac{1}{2.5} \left(10 + \frac{32.2 \times 3}{2} - \frac{3^2}{24} \right) = \boxed{23.17 \text{ rad/s}} \text{ Ans.}$$

$$v_{Pt} = r_{Pt} \omega_{Pt} = 4 \times \frac{1}{2.5} \left(10 + \frac{gt}{2} - \frac{t^2}{24} \right) \quad \text{--- (3)}$$

$$\therefore v_{P3} = \frac{4}{2.5} \left(10 + \frac{32.2 \times 3}{2} - \frac{3^2}{24} \right) = \boxed{92.68 \text{ fps}} \text{ Ans.}$$

$$a_{nPt} = r_P \omega_{Pt}^2 = 4 \times \frac{1}{2.5^2} \left(10 + \frac{gt}{2} - \frac{t^2}{24} \right)^2 \quad \text{--- (4)}$$

$$\therefore a_{nP3} = \frac{4}{2.5^2} \left(10 + \frac{32.2 \times 3}{2} - \frac{3^2}{24} \right)^2 = \boxed{2147.39 \text{ fps}^2} \text{ Ans}$$

$$a_{tPt} = r_P \alpha_{Pt} = r_P \cdot \frac{d\omega_{Pt}}{dt} = 4 \times \frac{d}{dt} \left[\frac{1}{2.5} \left(10 + \frac{gt}{2} - \frac{t^2}{24} \right) \right]$$

$$= \frac{4}{2.5} \left(\frac{g}{2} - \frac{t}{12} \right) \quad \text{--- (5)}$$

$$\therefore a_{tP3} = \frac{4}{2.5} \left(\frac{32.2}{2} - \frac{3}{12} \right) = \boxed{25.36 \text{ fps}^2} \text{ Ans.}$$

962/P.280

Here, $\alpha = 0.1t$

$$\omega_0 = 5 \text{ rad/s}$$

$$t = 10 \text{ s}$$

$$r = 6 \text{ inch}$$

$$a_t = ? \quad a_n = ?$$

Solⁿ

$$\text{at } t=10 \text{ s, } \alpha = 0.1 \times 10 = 1 \text{ rad/s}^2$$

$$\therefore a_t = r\alpha = 6 \times 1 = \boxed{6 \text{ in/s}^2} \text{ Ans.}$$

$$\alpha = \frac{d\omega}{dt}$$

$$\Rightarrow d\omega = \alpha dt$$

$$\Rightarrow \int_5^{\omega_f} d\omega = \int_0^{10} 0.1t dt$$

$$\Rightarrow [\omega]_5^{\omega_f} = \frac{0.1}{2} [t^2]_0^{10}$$

$$\Rightarrow \omega_f - 5 = 0.05(10^2 - 0)$$

$$\therefore \omega_f = 10 \text{ rad/s}$$

$$a_n = r\omega_f^2 = 6 \times 5^2 = \boxed{150 \text{ in/s}^2} \text{ Ans.}$$

963/P.280

Here, $\alpha = -4\theta^{1/2}$ $a_{nf} = ?$
 $\omega_0 = 50 \text{ rad/s}$ $a_{tf} = ?$
 $\theta_f = 7 \text{ rev} = 7 \times 2\pi = 14\pi \text{ rad}$
 $r = 18 \text{ in.}$

Solⁿ

We know, $\alpha d\theta = \omega d\omega$

$$\Rightarrow -4\theta^{1/2} d\theta = \omega d\omega$$

$$\Rightarrow -4 \int_0^{14\pi} \theta^{1/2} d\theta = \int_{50}^{\omega_f} \omega d\omega$$

$$\Rightarrow -4 \left[\theta^{3/2} \cdot \frac{2}{3} \right]_0^{14\pi} = \left[\frac{\omega^2}{2} \right]_{50}^{\omega_f}$$

$$\Rightarrow -\frac{8}{3} (14\pi)^{3/2} = \frac{1}{2} (\omega_f^2 - 50^2)$$

$$\Rightarrow \omega_f^2 = -\frac{16}{3} (14\pi)^{3/2} + 50^2$$

$$\therefore \omega_f = 30.75 \text{ rad/s.}$$

$$\alpha_f = -4\theta_f^{1/2} = -4 \times (14\pi)^{1/2} = -26.52 \text{ rad/s}^2$$

$$a_{tf} = r\alpha_f = 18 \times (-26.52) \text{ in/s}^2 = -39.78 \text{ fps}^2$$

-ve means velocity is reducing
Ans.

$$a_{nf} = r\omega_f^2 = 18 \times 30.75^2 \text{ in/s}^2 = 1418.34 \text{ fps}^2$$

Ans.

965/P.281

Here, $a_t = (s+6)^{1/2}$, circular path, $r = 600$ ft

at $t=0$, $v_0 = 0$

$t = t_f$, $s = 100$ ft

Find $\Rightarrow a_{nf}$ and a_{tf}

Solⁿ

$$a_{tf} = (100+6)^{1/2} = 10.29 \text{ fps}^2$$

For rectilinear motion, $a ds = v dv$

Here, $a_t ds = v dv$

$$\Rightarrow (s+6)^{1/2} ds = v dv$$

$$\Rightarrow \int_0^{100} (s+6)^{1/2} ds = \int_0^{v_f} v dv$$

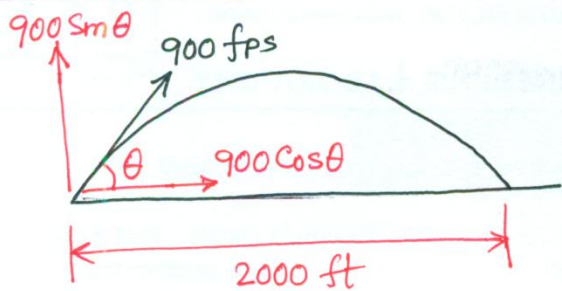
$$\Rightarrow \frac{2}{3} \left[(s+6)^{3/2} \right]_0^{100} = \frac{1}{2} [v^2]_0^{v_f}$$

$$\Rightarrow v_f^2 = \frac{4}{3} (100+6)^{3/2}$$

$$\therefore v_f = 38.15 \text{ fps}$$

$$\therefore a_{nf} = \frac{v_f^2}{r} = \frac{38.15^2}{600} = 2.43 \text{ fps}^2$$

977/P. 281



$\theta = ?$

Considering horizontal motion

$$2000 = (900 \cos \theta) \cdot t \quad \text{--- (1)}$$

Considering vertical motion (downward +ve)

$$0 = -(900 \sin \theta) \cdot t + \frac{1}{2} g t^2 \quad \text{--- (2)}$$

$$\text{From eq}^n \text{ (1)} \quad 900 \cos \theta = \frac{2000}{t} \quad \text{--- (3)}$$

$$\text{From eq}^n \text{ (2)} \quad 900 \sin \theta = 16.1 t \quad \text{--- (4)}$$

Now taking square of both sides of eqⁿ (3) & (4) and adding —

$$900^2 = \frac{2000^2}{t^2} + 16.1^2 t^2$$

$$\Rightarrow 259.21 t^4 + 2000^2 - 900^2 t^2 = 0$$

$$\Rightarrow t^4 - 3124.88 t^2 + 15431.5 = 0$$

$$\Rightarrow t^2 = \frac{3124.88 \pm \sqrt{3124.88^2 - 4 \times 15431.5}}{2}$$

$$= \frac{3124.88 \pm 3114.99}{2}$$

$$= 3119.94 \text{ s}, 4.95 \text{ s}$$

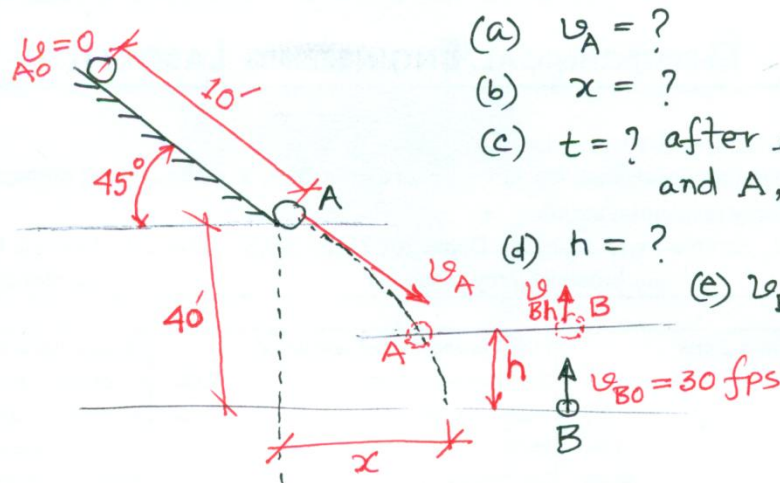
$$\therefore t = 55.86 \text{ s}, 2.22 \text{ s}$$

$$\text{From eq}^n \text{ (4)} \quad \theta = \sin^{-1} \left(\frac{16.1 t}{900} \right)$$

$$\text{when } t = 55.86 \text{ s}, \quad \theta = \boxed{87.82^\circ} \text{ Ans}$$

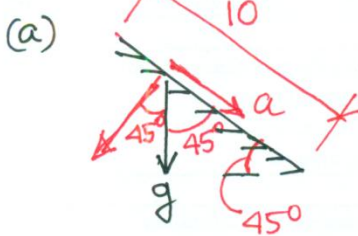
$$t = 2.22 \text{ s}, \quad \theta = \boxed{2.28^\circ} \text{ Ans}$$

981/P. 281



- (a) $v_A = ?$
 (b) $x = ?$
 (c) $t = ?$ after A leaves the plane and A, B are at same level
 (d) $h = ?$
 (e) $v_{Bh} = ?$

Solⁿ

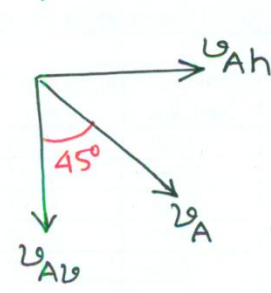


Accelⁿ along the plane, $a = g \cos 45^\circ$
 $= 32.2 \times \cos 45^\circ$
 $= 22.77 \text{ fps}^2$

Now $v_A^2 = 2as$
 $= 2 \times 22.77 \times 10$

$\therefore v_A = 21.34 \text{ fps}$ Ans.

(b) Let t_1 be the time taken by body A to drop from end of the plane to the ground.



$v_{Ah} = v_{Av} = v_A \cos 45^\circ = 21.34 \cos 45^\circ$
 $= 15.09 \text{ fps}$

For vertical component of the motion

$40 = v_{Av} \cdot t_1 + \frac{1}{2} g t_1^2$

$\Rightarrow 40 = 15.09 t_1 + \frac{1}{2} \times 32.2 \times t_1^2$

$\Rightarrow 16.1 t_1^2 + 15.09 t_1 - 40 = 0$

$\therefore t_1 = \frac{-15.09 \pm \sqrt{15.09^2 + 4 \times 16.1 \times 40}}{2 \times 16.1}$

$= \frac{-15.09 \pm 52.95}{32.2}$

$= 1.176 \text{ sec. (taking +ve value only)}$

$\therefore x = v_{Ah} \cdot t_1 = 15.09 \times 1.176 = 17.75 \text{ ft}$ Ans.

(c) $t \rightarrow$ time elapsed after A leaves the plane when both A & B are at the same elevation.

$$\begin{array}{l} \text{for body A} \rightarrow 40 - h = 15.09t + \frac{1}{2}gt^2 \quad \text{--- ①} \\ \text{for body B} \rightarrow -h = -30t + \frac{1}{2}gt^2 \quad \text{--- ②} \end{array} \left. \vphantom{\begin{array}{l} \text{for body A} \\ \text{for body B} \end{array}} \right\} \begin{array}{l} \text{Taking} \\ \text{downward} \\ \text{+ve} \end{array}$$

$$\text{①} - \text{②} \text{ gives, } 40 = 45.09t$$

$$\therefore t = 0.89 \text{ sec.} \quad \text{Ans.}$$

(d) Substituting $t = 0.89 \text{ s.}$ in eqⁿ ②

$$h = 30 \times 0.89 - \frac{1}{2} \times 32.2 \times 0.89^2$$

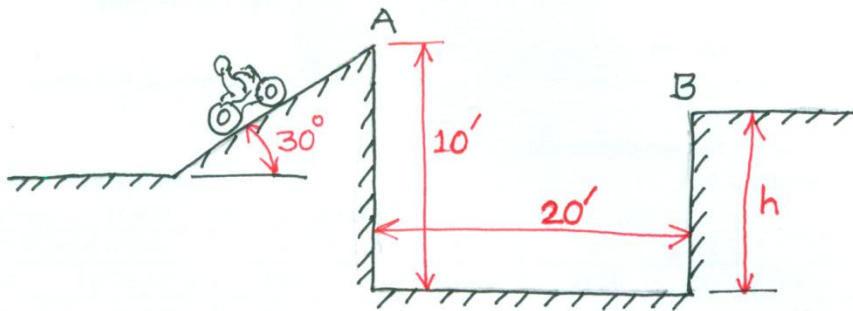
$$= 13.95 \text{ ft} \quad \text{Ans.}$$

$$(e) \quad v_{Bh} = v_{B0} + gt$$

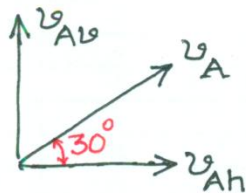
$$= -30 + 32.2 \times 0.89$$

$$= -1.34 \text{ fps (-ve means upward)} \quad \text{Ans.}$$

983/P. 282



$$v_A = 75 \text{ mph} = \frac{75 \times 3 \times 1760}{60 \times 60} \text{ fps.} = 110 \text{ fps.}$$



$$v_{Ah} = v_A \cos 30^\circ = 95.26 \text{ fps}$$

$$v_{Av} = v_A \sin 30^\circ = 55 \text{ fps}$$

For horizontal motion, $s = v_{Ah} \cdot t$

$$\Rightarrow 20 = 95.26 \times t$$

$$\therefore t = 0.21 \text{ s.}$$

Considering downward direction +ve, for vertical motion

$$10 - h = v_{Av} t + \frac{1}{2} g t^2$$

$$\Rightarrow 10 - h = (-55) \times 0.21 + \frac{1}{2} \times 32.2 \times 0.21^2$$

$$\therefore h = \boxed{20.84 \text{ ft.}} \text{ Ans.}$$

987/P.282

$$x^2 + 50y = 10,000$$

Differentiating w.r.t. 't'

$$2x \frac{dx}{dt} + 50 \frac{dy}{dt} = 0$$

$$\Rightarrow 2x v_x + 50 v_y = 0 \quad \text{--- (i)}$$

Again differentiating w.r.t. 't'

$$2 v_x \frac{dx}{dt} + 50 \frac{dv_y}{dt} = 0 \quad \left[\text{Notice that } v_x \text{ is mentioned as constant} \right]$$

$$\Rightarrow 2 v_x^2 + 50 a_y = 0$$

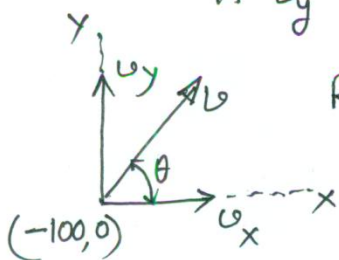
$$\Rightarrow 2 v_x^2 + 50 \times (-g) = 0$$

$$\therefore v_x = \sqrt{\frac{50g}{2}} = \sqrt{\frac{50 \times 32.2}{2}} = 28.37 \text{ fps}$$

Now from eqⁿ (i), at point (-100, 0)

$$2x(-100) \times 28.37 + 50 v_y = 0$$

$$\therefore v_y = 113.48 \text{ fps}$$



Resultant velocity at (-100, 0)

$$= \sqrt{v_x^2 + v_y^2}$$

$$= \sqrt{28.37^2 + 113.48^2}$$

$$= \boxed{116.97 \text{ fps}} \quad \text{Ans}$$

$$\tan \theta = \frac{v_y}{v_x} \Rightarrow \theta = \tan^{-1} \frac{v_y}{v_x} = \tan^{-1} \frac{113.48}{28.37} = \boxed{75.96^\circ} \quad \text{Ans.}$$

988/P. 282

Given, tangential velocity = Constant = 12 fps

$$\text{i.e. } v_x^2 + v_y^2 = 12^2 \quad \text{--- (1)}$$

Now $y = e^x$

$$\Rightarrow \frac{dy}{dt} = e^x \cdot \frac{dx}{dt}$$

$$\Rightarrow v_y = y \cdot v_x \quad \text{--- (2)}$$

From (1) and (2)

$$v_x^2 + y^2 v_x^2 = 144$$

$$\Rightarrow v_x^2 (1 + y^2) = 144$$

$$\therefore v_x = \frac{12}{\sqrt{1 + y^2}}$$

at $y = 10$ ft, $v_x = \frac{12}{\sqrt{1 + 10^2}} = \boxed{1.194 \text{ fps}}$ Ans.

and from (2), $v_y = 10 \times 1.194 = \boxed{11.94 \text{ fps}}$ Ans.

989/P.282

$$x^2 = 36y$$

Differentiating w.r.t. 't'

$$2x \frac{dx}{dt} = 36 \frac{dy}{dt}$$

$$\Rightarrow 2x v_x = 36 v_y$$

$$\Rightarrow x v_x = 18 v_y$$

$$\text{at } x = 40 \text{ ft, } 40 v_x = 18 v_y$$

$$\therefore v_x = 0.45 v_y \quad \text{--- (1)}$$

Given, tangential velocity = 12 fps

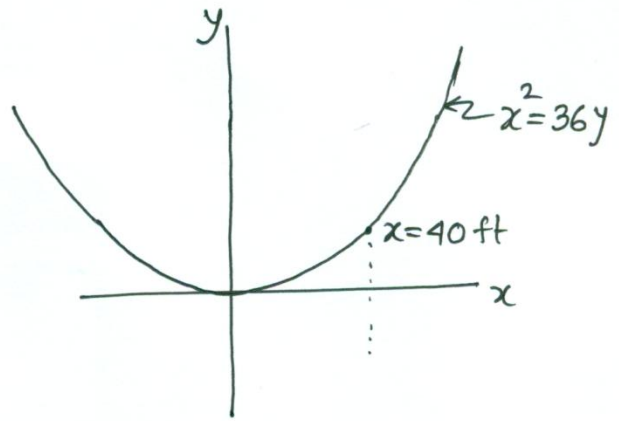
$$\text{i.e. } v_x^2 + v_y^2 = 12^2 \quad \text{--- (2)}$$

Substituting (1) into (2)

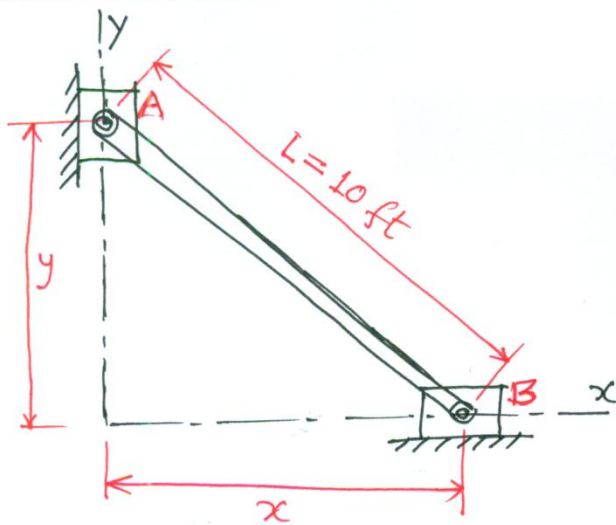
$$(0.45 v_y)^2 + v_y^2 = 12^2$$

$$\therefore v_y = \boxed{10.94 \text{ fps}} \text{ Ans.}$$

$$\text{Now from eqn (1) } v_x = 0.45 \times 10.94 = \boxed{4.92 \text{ fps}} \text{ Ans.}$$



990/P.282



Given

$$L = 10 \text{ ft}$$

$$\text{when } x = 8 \text{ ft, } v_B = 20 \text{ fps} \rightarrow$$

$$a_B = -15 \text{ fps}^2 \leftarrow$$

$$v_A = ? \quad a_A = ?$$

$$\text{Here, } x^2 + y^2 = 10^2 \quad \text{--- (1)}$$

Differentiating eqⁿ (1) w.r.t. 't'

$$2x \frac{dx}{dt} + 2y \cdot \frac{dy}{dt} = 0$$

$$\Rightarrow x v_B + y v_A = 0 \quad \text{--- (2)}$$

$$\text{When } x = 8 \text{ ft, } v_B = 20 \text{ fps, } y = \sqrt{10^2 - 8^2} = 6 \text{ ft}$$

substituting in eqⁿ (2)

$$8 \times 20 + 6 \times v_A = 0$$

$$\therefore v_A = -26.67 \text{ fps, } \text{-ve sign means motion of A is downward}$$

Ans.

Differentiating (2) w.r.t. 't'

$$x \cdot \frac{dv_B}{dt} + v_B \cdot \frac{dx}{dt} + y \frac{dv_A}{dt} + v_A \cdot \frac{dy}{dt} = 0$$

$$\Rightarrow x a_B + v_B^2 + y a_A + v_A^2 = 0$$

For the instant in consideration

$$8 \times (-15) + 20^2 + 6 \times a_A + (-26.67^2) = 0$$

$$\therefore a_A = -165.21 \text{ fps}^2 \text{-ve means } \downarrow$$

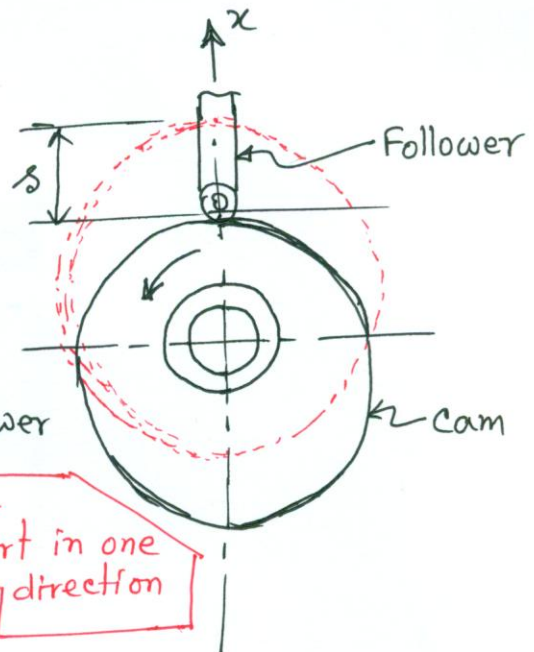
Ans.

997/P.283

Given $s = 3$ inch with
harmonic motion

Cam speed = 60 rpm

$v_{\max} = ?$ $a_{\max} = ?$ for follower



Stroke \rightarrow Complete movement of a
reciprocating machine part in one
direction

For Harmonic motion

$$x = r \cos \omega t$$

$$\therefore v = \frac{dx}{dt} = -r\omega \sin \omega t$$

$$\therefore a = \frac{dv}{dt} = -r\omega^2 \cos \omega t$$

$$\text{Here, } r = \frac{s}{2} = \frac{3}{2} = 1.5 \text{ inch}$$

$$\omega = 60 \text{ rpm} = \frac{60 \times 2\pi}{60} \text{ rad/s} = 2\pi \text{ rad/s}$$

$$\therefore v_{\max} = r\omega = 1.5 \times 2\pi = 9.42 \text{ in per sec.}$$

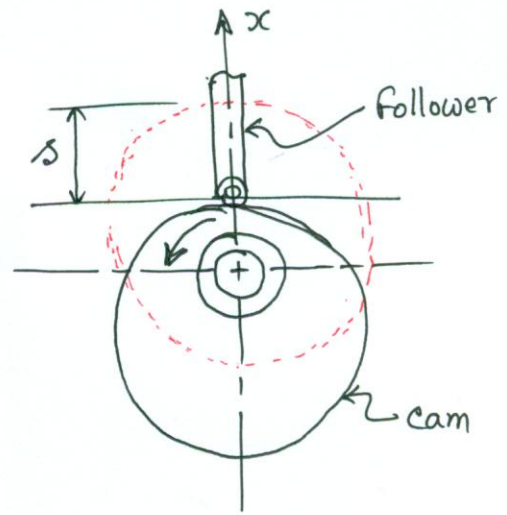
$$= \boxed{0.79 \text{ fps}} \text{ Ans.}$$

$$\text{and } a_{\max} = r\omega^2 = 1.5 \times (2\pi)^2 = 59.16 \text{ in per sec.}^2$$

$$= \boxed{4.93 \text{ fps}^2} \text{ Ans.}$$

998/P.283

Given: $T = 2$ sec.
Harmonic motion
 $r = \frac{5}{2} = 2.5$ inch
 $v_{\max} = ?$ $a_{\max} = ?$



Because of Harmonic motion of the follower

$$x = r \cos \omega t$$

$$\therefore v = \frac{dx}{dt} = -r\omega \sin \omega t$$

$$a = \frac{dv}{dt} = -r\omega^2 \cos \omega t$$

$$\text{Here, } \omega = \frac{2\pi}{T} = \frac{2\pi}{2} = \pi \text{ rad/s}$$

$$\therefore v_{\max} = r\omega = 2.5 \times \pi = \boxed{7.85 \text{ inch/s.}} \text{ Ans.}$$

$$a_{\max} = r\omega^2 = 2.5 \times \pi^2 = \boxed{24.67 \text{ inch/s.}} \text{ Ans.}$$