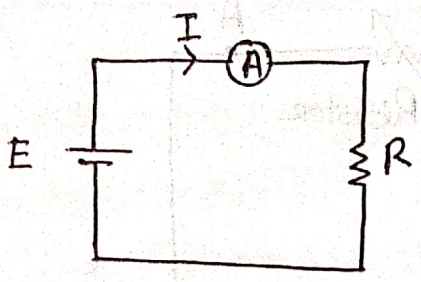


EEE

8th-D Day
20-10-19

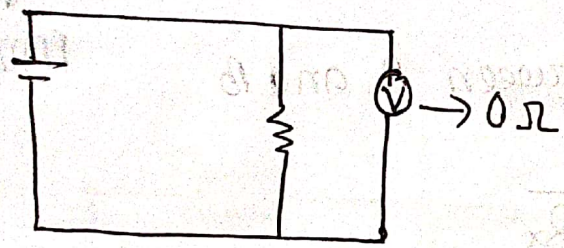
Current measurement:



Resistance low হলে পরিমাপ বেশি হবে

$$I = \frac{E}{R}$$

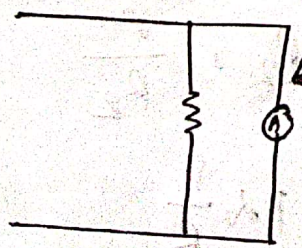
→ এখানে series এ অল্প পরিমাপ measure করতে পারবে না।



parallel যোগ করলে পরিমাপ বেশি

Q. কোনো v মিটার কে series এ লাগানো যাবে কি?

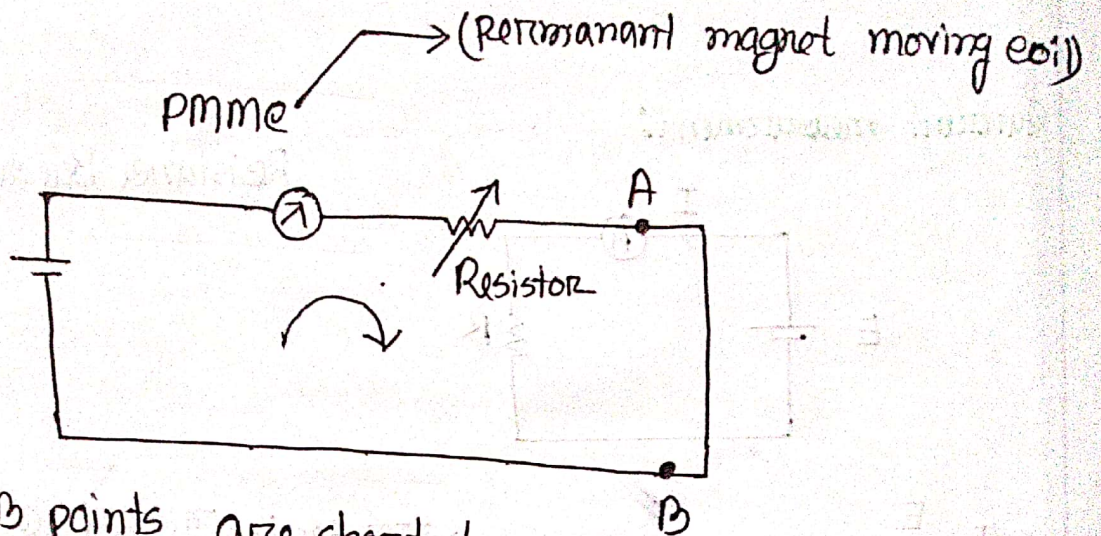
Q. " A " " " parallel " " " " " ?



→ এমন এটা short circuit এর মতো কাজ করবে, তাই অ্যামিটার কে parallel এ লাগানো যাবে না।

A → internal resistance কম তাই parallel এ লাগানো যাবে না।

Resistance measurement:

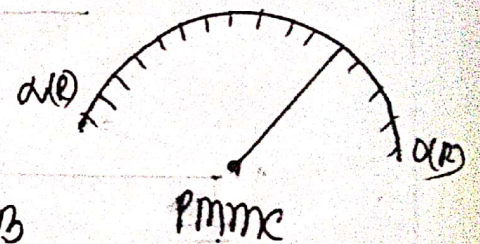


(i) A and B points are shorted

Full scale deflection current $I_g = \frac{E}{R}$

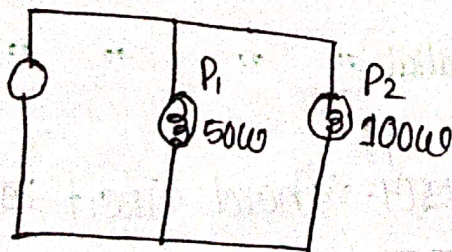
(ii) A and B are open

(iii) R_x is connected between A and B



$$I_m = \frac{E}{R + R_x}$$

Power measurement:



$$P_1 = VI_1$$

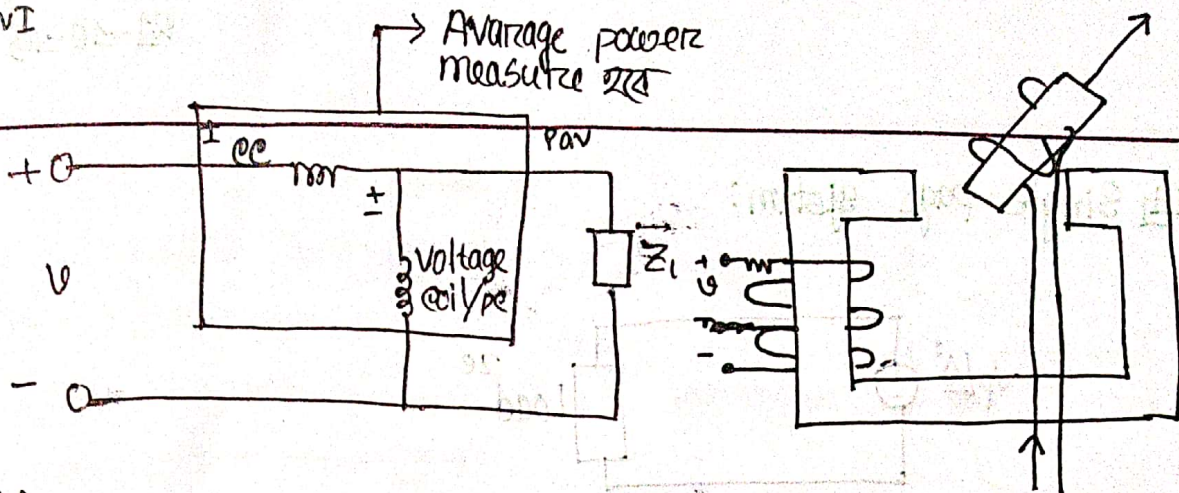
$$P_1 = \frac{V^2}{R_1}$$

$$P_2 = \frac{V^2}{R_2}$$

$$P \propto \frac{1}{R}$$

Watt meter

$P = VI$



$v(t) = V_m \cos(\omega t + \phi_v)$

$i(t) = I_m \cos(\omega t + \phi_i)$

$P = v(t) \cdot i(t)$

$P = V_{rms} \cdot I_{rms} \cos(\phi_v - \phi_i)$

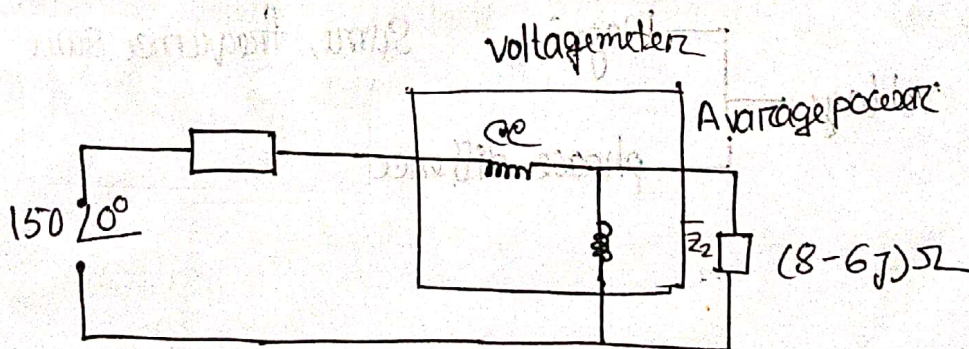
$= \frac{1}{2} V_m I_m \cos(\phi_v - \phi_i)$

$\bar{v} = V_m \angle \phi_v$

$\bar{i} = I_m \angle \phi_i$

Q. ਕਿਛਾਕੇ watt meter ਦਿਖਾਏ power & measure ਕਰਾਏ ?
 ⇒ ± ਪਰਕਾਰ ਦਿਖਾਏ ਦਿੱਤੇ ਸੰਕੇਤ ਨਾ ਹੋਣ deflection ਦਿਖਾਏ
 ⇒ 2 ਠੀਕ coil ਵਰਤਾਏ ਕਰਾਏ
 ⇒ equation ਜੁੜਾਏ

Ex: 11.16



$$\bar{S} = \bar{V}_{rms} \cdot \bar{I}_{rms}$$

$$= \sqrt{V_{rms}} \cdot \sqrt{I_{rms}} \angle \phi_v - \phi_i$$

$$= \frac{V_{rms} I_{rms}}{\cos(\phi_v - \phi_i)}$$

$P = V_{rms} \cdot I_{rms} \cos(\phi_v - \phi_i)$

$\bar{S} = \frac{V_{rms} \cdot I_{rms} \cos(\phi_v - \phi_i)}{\text{Real power}} + j \frac{V_{rms} \cdot I_{rms} \sin(\phi_v - \phi_i)}{\text{Reactive power}}$

$150 \sin(\omega t + 30^\circ)$

$I_{rms} = \frac{150 \angle 30^\circ}{12 + j10 + 8 - j6} = 7.35 \angle -11.30^\circ \text{ A} = (7.2 - j1.4) \text{ A}$

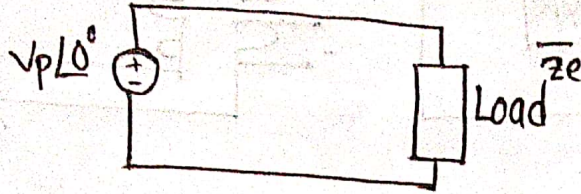
$\bar{V}_{rms} = \bar{I}_{rms} (8 - j6)$
 $= 73.54 \angle -48.17^\circ$
 $= (49.045 - 54.8j) \text{ V}$

$\bar{S} = \bar{V}_{rms} \cdot \bar{I}_{rms}$
 $= (49.03 - j54.8)(7.2 + j1.42)$
 $= (430.7 - 732.6j) \text{ VA}$

Practise P. - 11.16

watt meter reading = 430.7W
 volt meter reading = 324.6VAR

Single phase system:

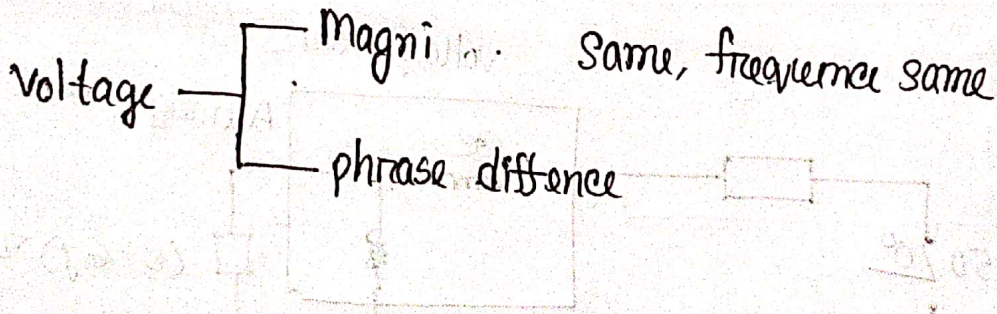


Polyphase system: → অনেকগুলো source থাকবে

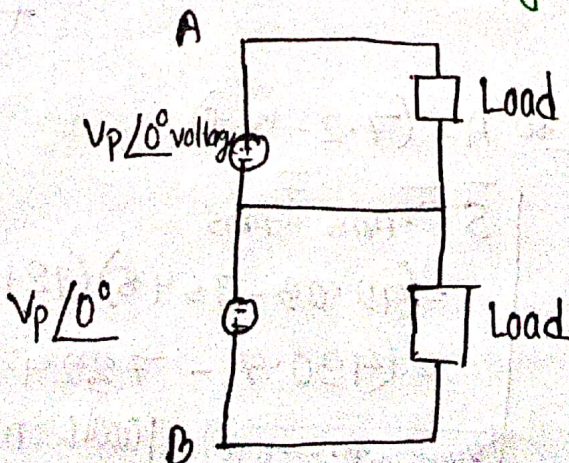
→ অনেক ধরনের voltage থাকবে

voltage magnitude, phase থাকবে

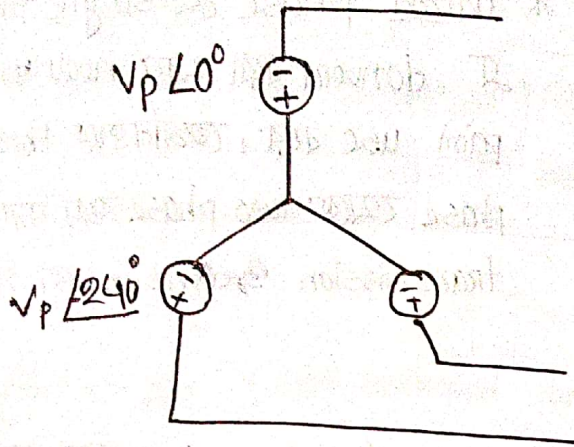
size/frequency same



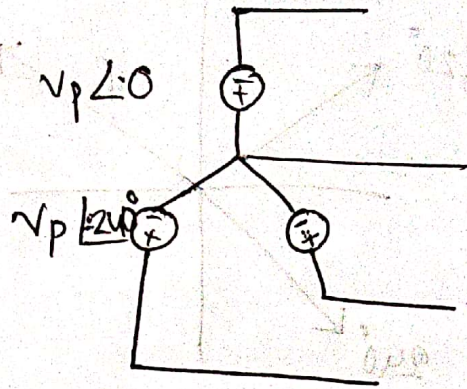
Single phase two wire system:



Single phase three wire system

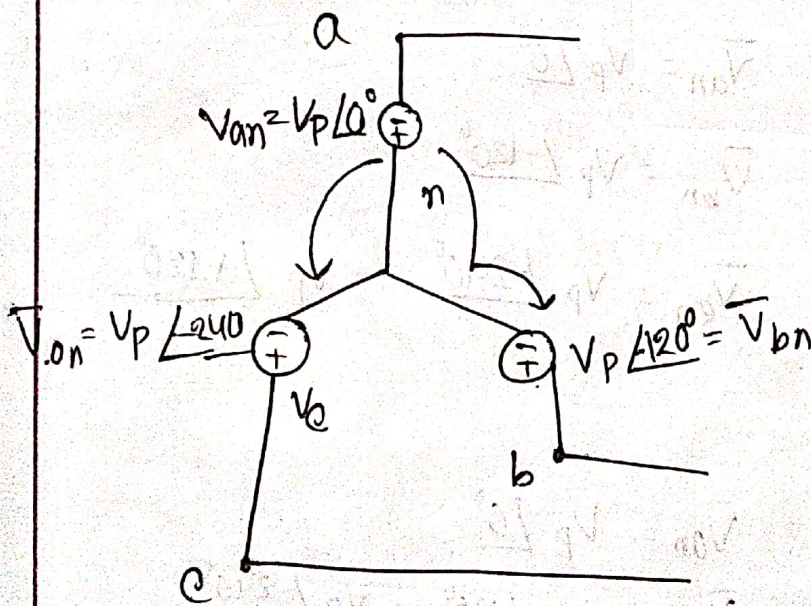


Three phase three wire system

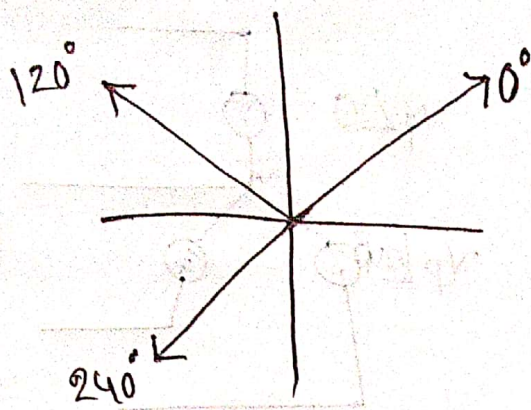


Three phase four wire system

Three phase system is produced by a generator consisting of three sources having same magnitude and frequency but out of phase with each other by 120° .



Three phase four wire system



* Three phase ko single phase
 me convert krna krna neutral
 point use krna. Khatibahar three
 phase ko two phase krna krna. Khatibahar
 transmission 3 division krna krna.

/// Instantaneous power constant krna krna voltage loss krna krna
 krna phase me. single phase krna krna three phase me krna
 krna krna.

Phase sequence: Voltage krna order fig-1. (motor me rotation)

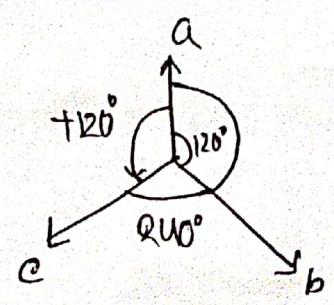
abc phase sequence clockwise / anti
 acb phase sequence clockwise (antahar)

abc phase sequence,

$$\bar{V}_{an} = V_p \angle 0^\circ$$

$$\bar{V}_{bn} = V_p \angle -120^\circ$$

$$\bar{V}_{cn} = V_p \angle -240^\circ = V_p \angle +120^\circ$$

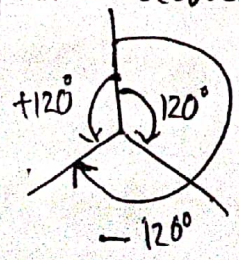


acb phase sequence,

$$\bar{V}_{an} = V_p \angle 0^\circ$$

$$\bar{V}_{bn} = V_p \angle 120^\circ = V_p \angle -240^\circ$$

$$\bar{V}_{cn} = V_p \angle -120^\circ$$



motor rotate कराने - abe abe abe ... sequence में चलते

एकान्तर क्रम में चलते हैं

abe या bea या cab या positive phase sequence

↳ clockwise rotation

acb acb acb → anti clockwise rotation

acb/cba/bca/neg phase sequence

Problem:

$$V_{an} = 200 \cos(\omega t + 10^\circ)$$

$$V_{bn} = 200 \cos(\omega t - 230^\circ)$$

$$V_{cn} = 200 \cos(\omega t - 110^\circ)$$

Determine phase sequence

Solve:

$$\bar{V}_{an} = 200 \angle 10^\circ \text{ V}$$

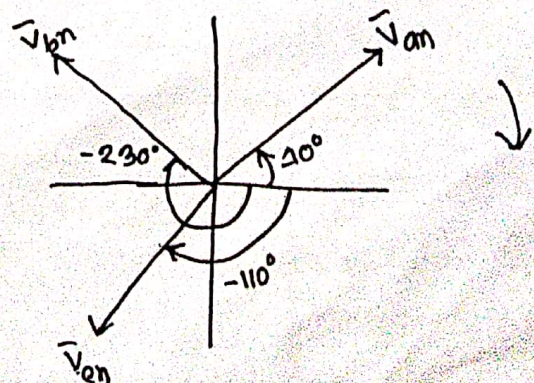
$$\bar{V}_{bn} = 200 \angle -230^\circ \text{ V}$$

$$\bar{V}_{cn} = 200 \angle -110^\circ \text{ V}$$

from fig.

acb phase sequence

(Ans)



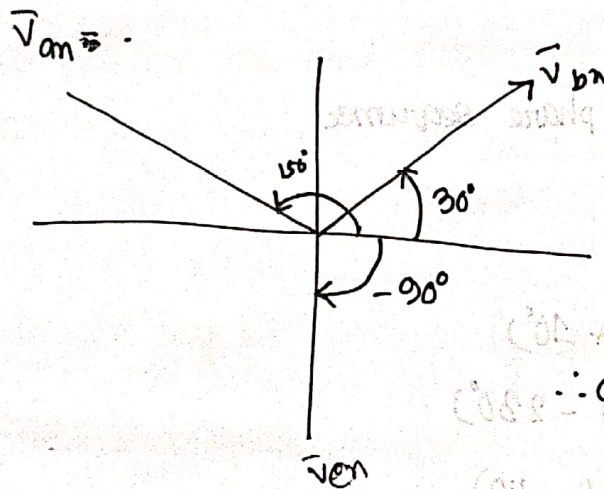
Problem:

$$\bar{V}_{an} = 200 \angle 150^\circ \text{ V}$$

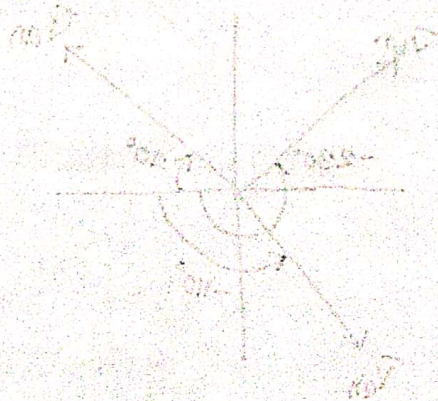
$$\bar{V}_{bn} = 200 \angle 30^\circ \text{ V}$$

$$\bar{V}_{cn} = 200 \angle -90^\circ \text{ V}$$

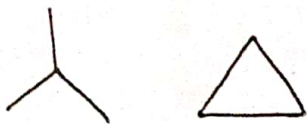
Solve:



\therefore abc phase sequence



☐ Balanced phase voltage → magnitude same
 Balanced load → magnitude phase is 120° out of each other
 Same \vec{I}_A , phase 3 same \vec{I}_C



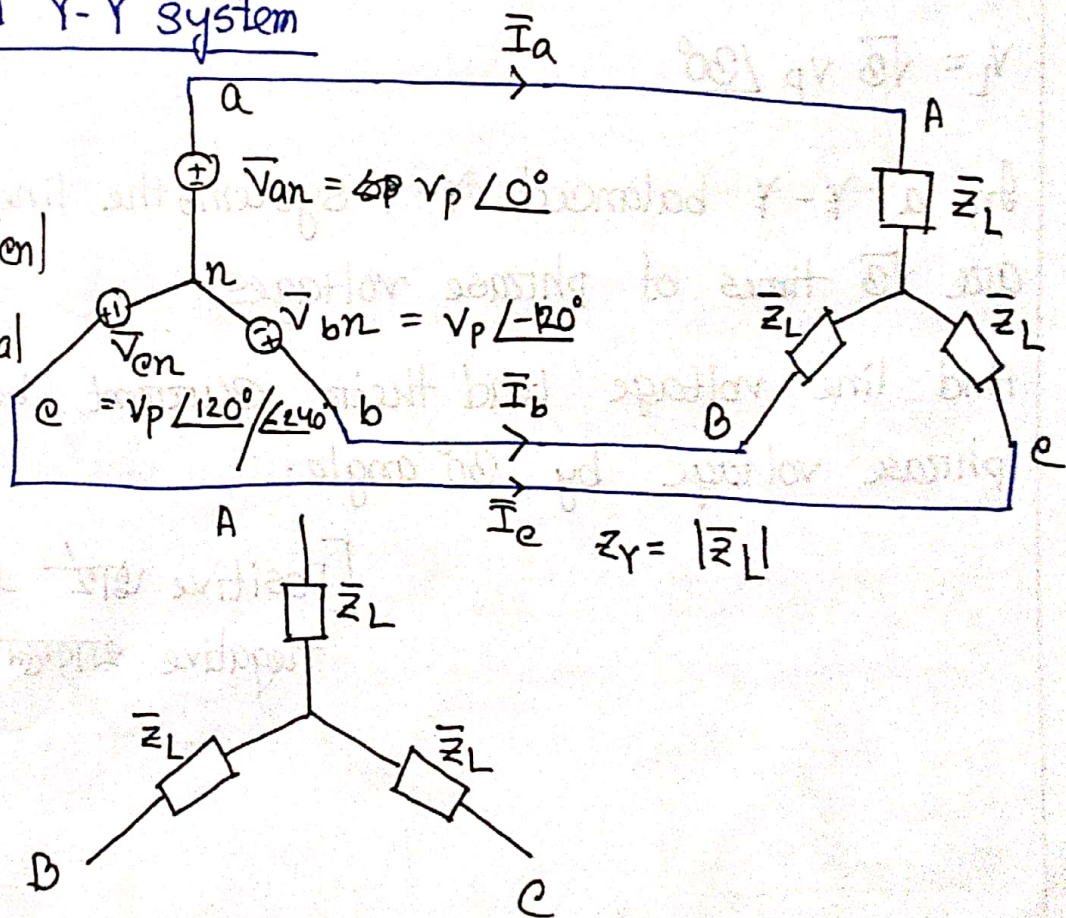
Balanced Y-Y system

abc phase

$$V_p = |\bar{V}_{an}| = |\bar{V}_{bn}| = |\bar{V}_{cn}|$$

$$V_L = |\bar{V}_{ab}| = |\bar{V}_{bc}| = |\bar{V}_{ca}|$$

$$= \sqrt{3} V_p$$



Line voltage

$$\bar{V}_{ab} = \bar{V}_{an} - \bar{V}_{bn} = V_p \angle 0^\circ - V_p \angle -120^\circ = V_p (\cos 0^\circ + j \sin 0^\circ - \cos(-120^\circ) - j \sin(-120^\circ))$$

$$= V_p \left(\frac{3}{2} + \frac{j\sqrt{3}}{2} \right) = \sqrt{3} V_p \angle 30^\circ$$

$$\bar{V}_{bc} = \bar{V}_{bn} - \bar{V}_{cn} = V_p \angle -120^\circ - V_p \angle 120^\circ = \sqrt{3} V_p \angle -90^\circ$$

$$\bar{V}_{ca} = \bar{V}_{cn} - \bar{V}_{an} = V_p \angle 120^\circ - V_p \angle 0^\circ = \sqrt{3} V_p \angle 150^\circ$$

$$\begin{aligned} \bar{V}_{be} &= \bar{V}_{bn} - \bar{V}_{en} = \sqrt{3} v_p \angle 30^\circ - 120^\circ \\ &= \sqrt{3} v_p \angle -90^\circ \end{aligned}$$

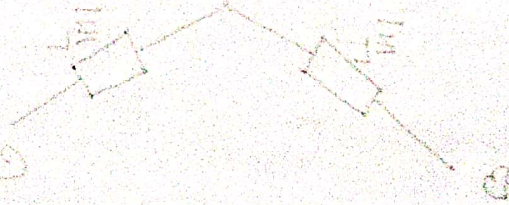
$$\begin{aligned} \bar{V}_{ca} &= \bar{V}_{cn} - \bar{V}_{an} = \sqrt{3} v_p \angle 30^\circ - 240^\circ \\ &= \sqrt{3} v_p \angle -210^\circ \end{aligned}$$

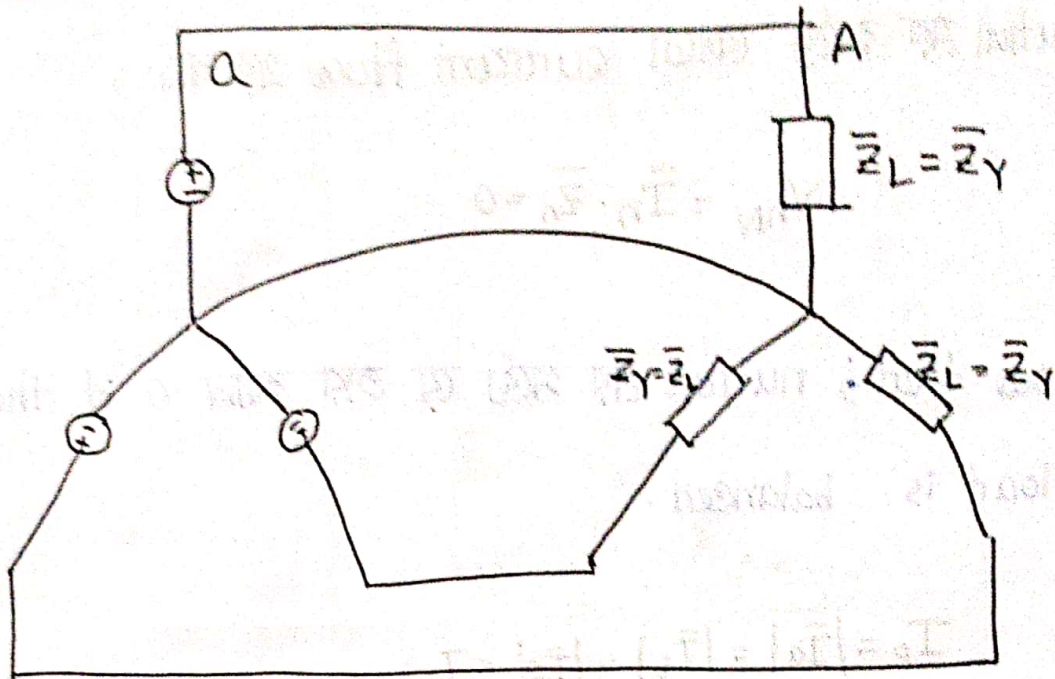
$$V_L = \sqrt{3} v_p \angle 30^\circ$$

In a Δ - Δ balanced Δ - Δ system, the line voltages are $\sqrt{3}$ times of phase voltages.

And line voltage lead their current bonding phase voltage by 30° angle.

[Positive Δ lead
negative Δ lag]

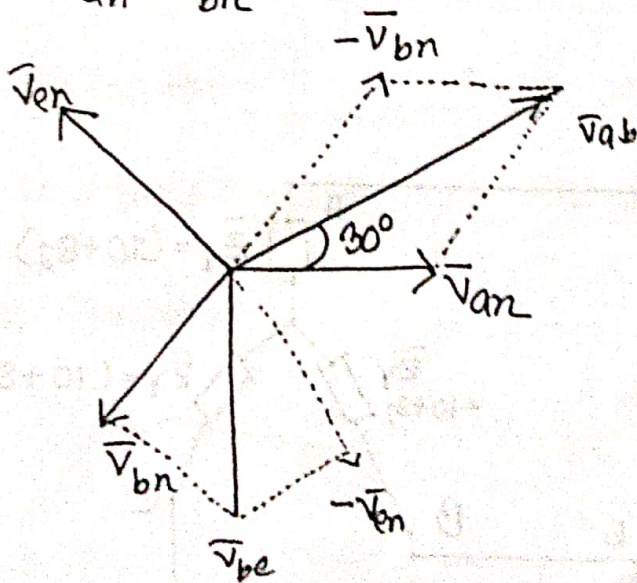




$$\bar{I}_n = \bar{I}_a + \bar{I}_b + \bar{I}_c$$

$$\bar{V}_{ab} = \bar{V}_{an} - \bar{V}_{bn}$$

$$\bar{V}_{bc} = \bar{V}_{bn} - \bar{V}_{cn}$$



$$\bar{I}_n = \bar{I}_a + \bar{I}_b + \bar{I}_c$$

$$\bar{I}_a = \frac{\bar{V}_{an}}{\bar{Z}_Y}$$

$$\bar{I}_b = \frac{\bar{V}_{bn}}{\bar{Z}_Y} = \frac{\bar{V}_{an} \angle -120^\circ}{\bar{Z}_Y}$$

$$= \bar{I}_a \angle -120^\circ$$

$$\bar{I}_c = \bar{I}_a \angle -240^\circ$$

Phasor diagram

$$\therefore \bar{I} = \bar{I}_a + \bar{I}_a \angle -120^\circ + \bar{I}_a \angle -240^\circ$$

$$= \bar{I}_a \left[\cos 0^\circ + j \sin 0^\circ + \cos(-120^\circ) + j \sin(-120^\circ) + \cos(-240^\circ) + j \sin(-240^\circ) \right]$$

$$\therefore \bar{I} = 0$$

$$V_L = \sqrt{3} V_P$$

$$I_L = I_P$$

∴ neutral त्र अर्थात् लोला current flow शून्य ना।

$$V_{nN} = \bar{I}_n \cdot \bar{Z}_n = 0$$

Q.9 Show that; neutral त्र अर्थात् लोला अर्थात् 0 if the # load is balanced.

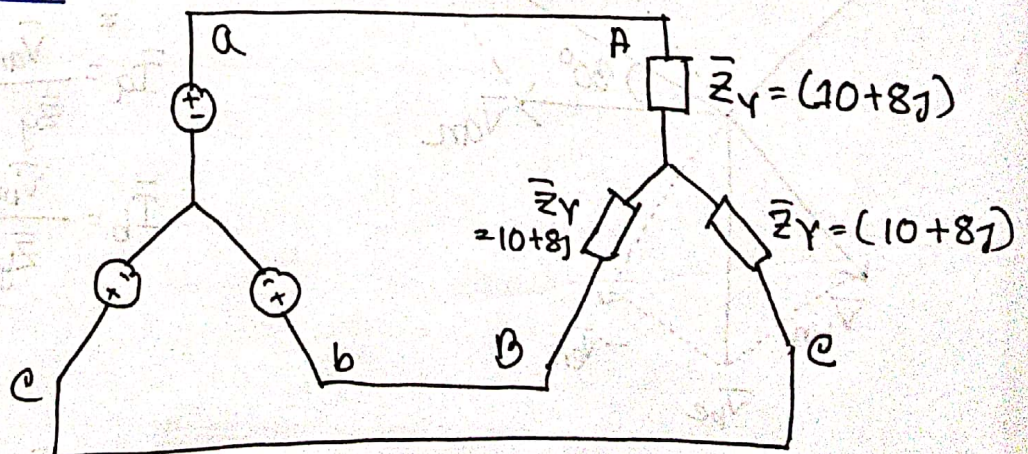
$$I_P = |\bar{I}_a| = |\bar{I}_b| = |\bar{I}_c| = I_L$$

Show that line current is equal to I_P in Y-Y system.

Problem 12.2

Ex: 12.2

abc
phase
sequence



$$\bar{V}_{an} = 110 \angle 0^\circ \text{ v}$$

$$\bar{Z}_Y = (10 + j8) \Omega$$

phase voltage,

$$\bar{V}_{an} = 110^\circ / 0^\circ \text{ V}$$

$$\bar{V}_{bn} = 110^\circ / -120^\circ \text{ V}$$

$$\bar{V}_{cn} = 110^\circ / -240^\circ \text{ V}$$

∴ Line voltage $\bar{V}_{ab} = \bar{V}_{an} - \bar{V}_{bn}$

$$= 110^\circ / 0^\circ - 110^\circ / -120^\circ$$

$$= 190.52 / 30$$

$$\bar{V}_{bc} = 190.52 / 30 - 120$$

$$= 190.52 / -90^\circ$$

$$\bar{V}_{ca} = 190.52 / 30 - 240^\circ = 190.52 / 30 + 120^\circ$$

$$= 190.52 / -210^\circ = 190.52 / 150^\circ$$

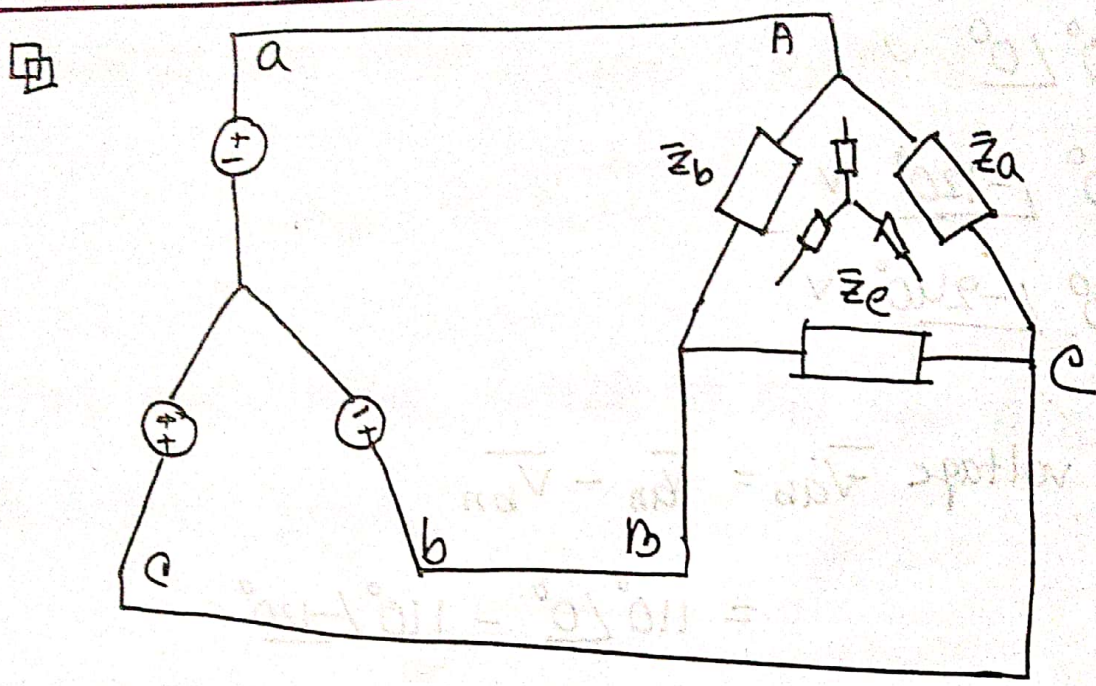
Phase current:

$$\bar{I}_a = \frac{\bar{V}_{an}}{Z}$$

$$= \frac{110 / 0^\circ}{10 + 8j} = 8.58 / -38.65$$

$$\bar{I}_b = 8.58 / -38.65 - 120^\circ = 8.58 / -158.65$$

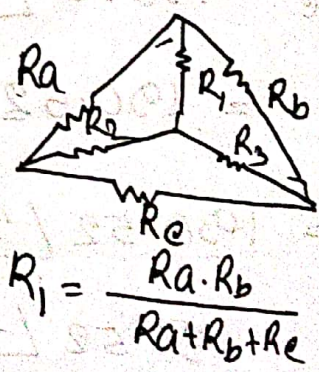
$$\bar{I}_c = 8.58 / -38.65 - 240^\circ = 8.58 / -278.65$$



$$\bar{Z}_{AN} = \frac{\bar{Z}_b \times \bar{Z}_c}{\bar{Z}_a + \bar{Z}_b + \bar{Z}_c}$$

$$= \frac{1}{3} \bar{Z}_a$$

$$\Rightarrow \bar{Z}_a = 3\bar{Z}_y$$

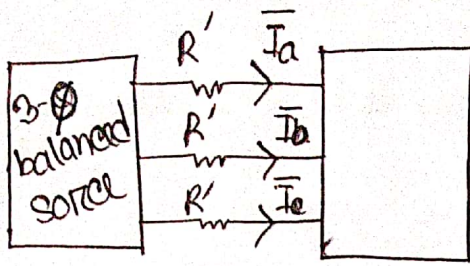


Ex Practice P 12.2

E x — 12.3

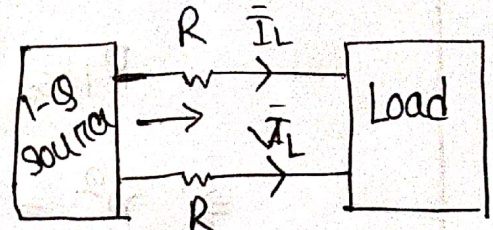
P.P — 12.3

□



(i) ...

$$R = \frac{\rho L}{A}$$



(ii)

Resistivity same
Same power loss

" " absolute

two wire 3-φ

System $I_L = \frac{P_L}{V_L}$

3-φ Three wire

System $I_L = |\bar{I}_a| = |\bar{I}_b| = |\bar{I}_c| = \frac{P_L}{\sqrt{3} V_L}$

$$P_{loss} = 3 I_L^2 R$$

$$= 3 \cdot \frac{P_L^2}{V_L^2} R$$

$$P'_{loss} = \frac{3 I_L^2 R'}{1}$$

$$= 3 \times \frac{P_L^2}{(\sqrt{3} V_L)^2} R'$$

$$= \frac{P_L^2}{V_L^2} R'$$

$$\frac{P_{loss}}{P'_{loss}} = 3 \cdot \frac{P_L^2}{V_L^2} R \times \frac{V_L^2}{P_L^2 \times R'} = \frac{2R}{R'}$$

$$= \frac{2 \times \rho \times l}{\pi r^2} \times \frac{R'' r'^2}{\rho l}$$

$$= \frac{2 r'^2}{r^2}$$

$$R = \rho \frac{l}{\pi r^2}$$

যেহেতু Power loss এর পরিমাণ সমান

$$P_{loss} = P'_{loss}$$

$$\Rightarrow r^2 = 2r'^2$$

$$\frac{\text{Material for 1-}\phi \text{ system}}{\text{Material for 3-}\phi \text{ system}} = \frac{2 \times \pi r^2 l}{3 \times \pi r'^2 l}$$
$$= \frac{4r'^2}{3r'^2}$$
$$= \frac{4}{3}$$

Material for 1- ϕ = 1.33 x Material for 3- ϕ system

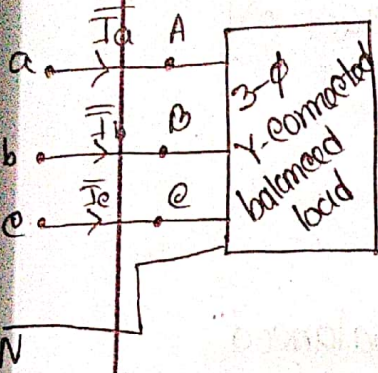
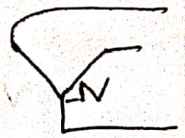
\therefore 1- ϕ system uses 33% more material than a 3- ϕ system

Q. Show that 1- ϕ system uses 33% more material than 3- ϕ system

R equal এর এই question এর উত্তর দেয়া হবে

Power distribution:

N = neutral point



$$i_a = \sqrt{2} I_p \cos(\omega t - \theta)$$

$$i_b = \sqrt{2} I_p \cos(\omega t - \theta - 120^\circ)$$

$$i_c = \sqrt{2} I_p \cos(\omega t - \theta + 120^\circ)$$

[θ का मतलब voltage दिया कि current पर current flow करेगा]

$$V_{AN} = \sqrt{2} V_p \cos \omega t$$

$$V_{BN} = \sqrt{2} V_p \cos(\omega t - 120^\circ)$$

$$V_{CN} = \sqrt{2} V_p \cos(\omega t + 120^\circ)$$

Total instantaneous power $P = P_a + P_b + P_c$

$$= V_{AN} I_a + V_{BN} I_b + V_{CN} I_c$$

$$= 2 V_p I_p \cos \omega t \cos(\omega t - \theta) + 2 V_p I_p \cos(\omega t - 120^\circ) \cos(\omega t - \theta - 120^\circ) + 2 V_p I_p \cos(\omega t + 120^\circ) \cos(\omega t - \theta + 120^\circ)$$

$$= V_p I_p \left[\cos \theta + \cos(2\omega t + \theta) + \cos(2\omega t - \theta - 240^\circ) + \cos(2\omega t - \theta + 240^\circ) \right]$$

$$= V_p I_p \left[3 \cos \theta + \cos(2\omega t - \theta) + 2 \cos(2\omega t - \theta) \cos 240^\circ \right]$$

$$= V_p I_p \left[3 \cos \theta + \cos(2\omega t - \theta) + 2 \cos(2\omega t - \theta) \left(-\frac{1}{2}\right) \right]$$

$$= V_p I_p \left[3 \cos \theta + \cos(2\omega t - \theta) - \cos(2\omega t - \theta) \right]$$

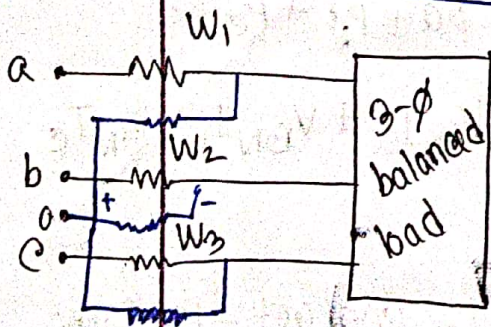
$$\therefore P = 3V_p I_p \cos \theta$$

\therefore Total instantaneous power of a 3- ϕ balanced system remains constant.

8. Total instantaneous power of a 3- ϕ balanced system remains constant \rightarrow Show that.

[Balanced system
मात्र 2- ϕ system use करें]

3- ϕ power measurement:



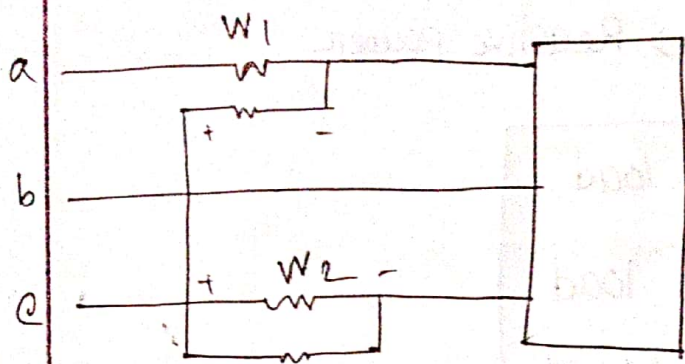
Total average power

$$P = P_1 + P_2 + P_3$$

Two wattmeter measured

a, b, c
3 ϕ source
2 Δ Y/ Δ
connected

2 Δ सिस्टम में
balanced 2 Δ
अथवा Neutral
current 0 पाऊंगा
मात्र 2 ϕ P=0



$$P_1 = \text{Re} [V_{ab} \bar{I}_a]$$

$$P_2 = \text{Re} [V_{cb} \bar{I}_c]$$

Total average power $P = P_1 + P_2$

$$= V_L I_L \cos(\theta + 30^\circ) + V_L I_L \cos(\theta - 30^\circ)$$

$$= V_L I_L [\cos(\theta + 30^\circ) + \cos(\theta - 30^\circ)]$$

$$= V_L I_L \cdot 2 \cos \theta \cos 30^\circ$$

$$= V_L I_L \cdot 2 \cos \theta \cdot \frac{\sqrt{3}}{2}$$

$$P = \sqrt{3} V_L I_L \cos \theta \rightarrow \text{Real power}$$

$$P_1 = \text{Re} [V_{ab} \bar{I}_a]$$

$$= V_{ab} I_a \cos(\theta + 30^\circ)$$

$$= V_L I_L \cos(\theta + 30^\circ)$$

$$P_2 = \text{Re} [V_{cb} \bar{I}_c]$$

$$= V_{cb} I_c \cos(\theta - 30^\circ)$$

$$= V_L I_L \cos(\theta - 30^\circ)$$

Q. discuss the two-wattmeter method for measuring average power?

$$P_2 - P_1 = V_L I_L \cos(\theta - 30^\circ) - V_L I_L \cos(\theta + 30^\circ)$$

$$= V_L I_L [\cos(\theta - 30^\circ) - \cos(\theta + 30^\circ)]$$

$$= V_L I_L \cdot 2 \sin \theta \sin 30^\circ$$

$$= V_L I_L \cdot 2 \cdot \sin \theta \cdot \frac{1}{2} = V_L I_L \sin \theta$$

$$P_3 - P_1 = V_L I_L \sin \theta \rightarrow \text{Reactive power}$$

- $P_1 = P_3 \rightarrow$ Resistive load
- $P_1 > P_3 \rightarrow$ Capacitive load
- $P_1 < P_3 \rightarrow$ Inductive load



Ex: 12.13

$$P_1 = V_L I_L \cos \theta = 100 \times 10 \times \cos 30^\circ = 866.025 \text{ W}$$

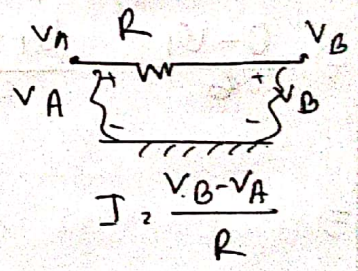
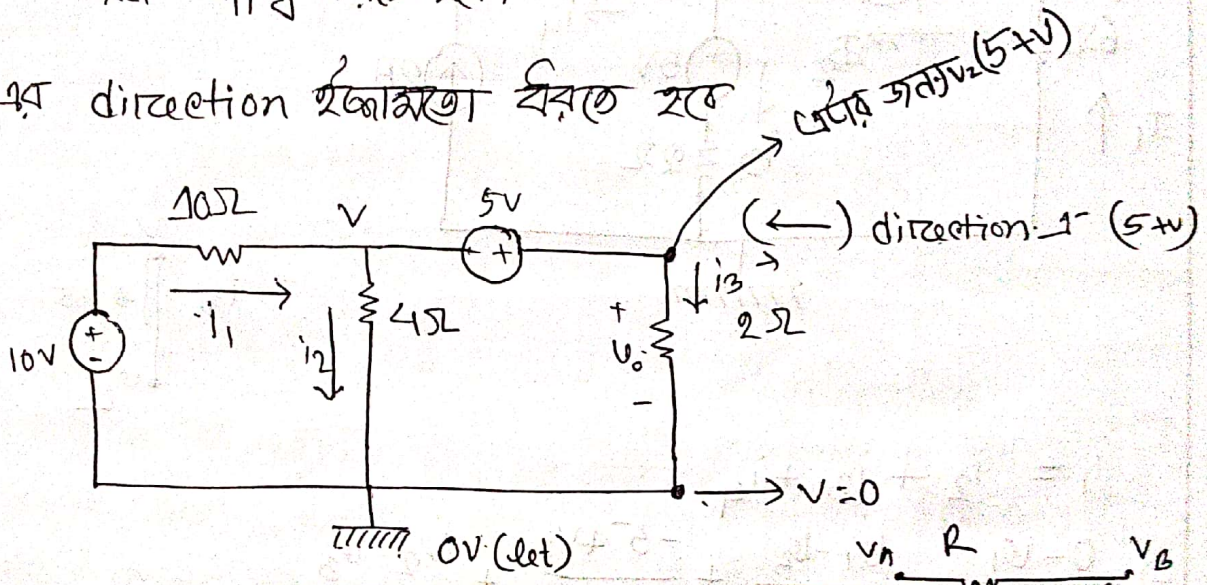
$$P_3 = V_L I_L \cos \theta = 100 \times 10 \times \cos 30^\circ = 866.025 \text{ W}$$

$$P_1 = P_3 \rightarrow \text{Resistive load}$$

Node analysis: @ একাধিক element connect থাকে

একটি reference node বিয়ে হবে
KCL apply করতে হবে,

Current এর direction ইচ্ছামতো বিয়ে হবে



$$i_1 = i_2 + i_3$$

$$\Rightarrow \frac{10-0}{10} = \frac{v-0}{4} + \frac{(5+v)-0}{2}$$

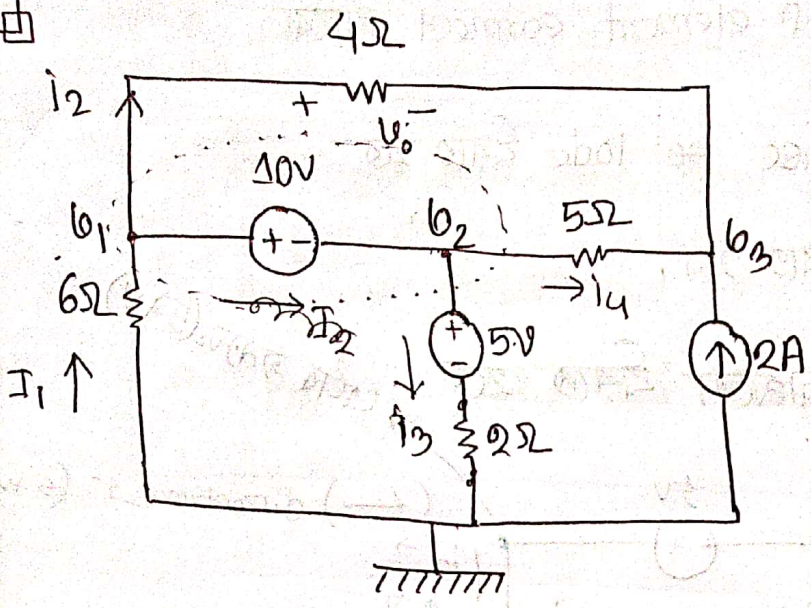
$$\Rightarrow -0 = -1.76$$

$$V_{AB} = V_A - V_B \text{ [KCL অনুযায়ী]}$$

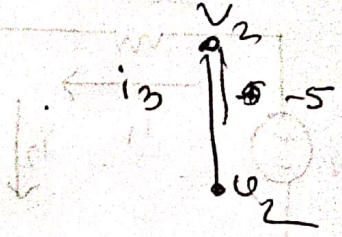


02-11-10
EEF (Kor 210)

EEF (Kor 210)



Supernode



$$i_1 = i_2 + i_3 + i_4$$

$$\Rightarrow \frac{0 - v_1}{6} = \frac{v_1 - v_3}{4} + \frac{-5 + v_2}{2} + \frac{v_2 - v_3}{5} \quad \text{--- (1)}$$

$$\Rightarrow \frac{4v_1 - 3v_2 + 3v_3}{20} = \frac{5v_2 - 5v_3}{10}$$

$$v_1 - v_2 = 10 \quad \text{--- (2)}$$

CT-3 → Three phase current

CT-4 → Electronic

Neces chapter

Electronics

Current conductor দিয়া শলে electrical

” ” ” ” Semiconductor দিয়া শলে electronics.

electrical

* electron এর জন্য

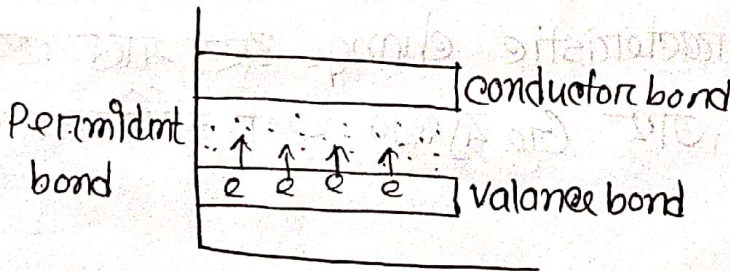
Current গঠিত হয়

* Conductor use করা হয়।

electronics

* electron 3 bond ২টা জন্য current গঠিত হয়।

* Semi conductor use করা হয়।



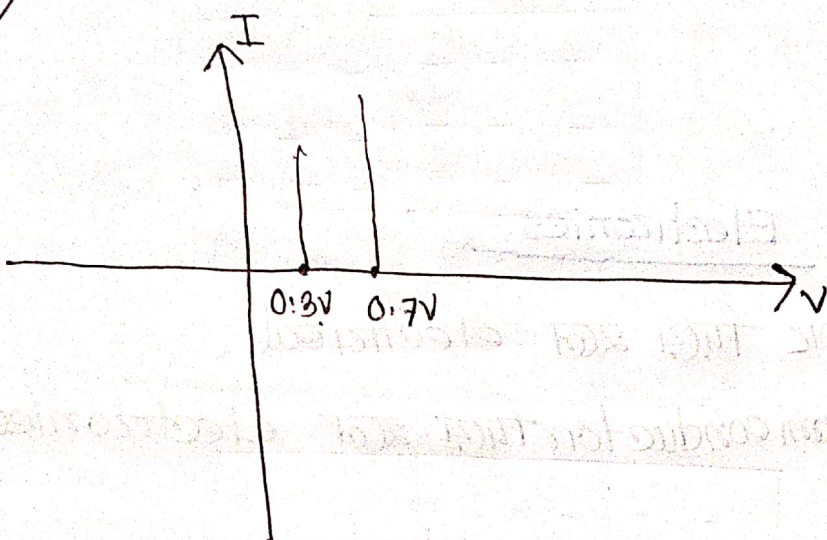
* Semi conductor এর conductor 3 valance bond এর মাঝে মাঝে, এর ২ ঘরনের reason এর কারণে current গঠিত হয়।

* Semi conductor:

| | |
|------------------------------|----------------------------------|
| Si → 0.7V (14) ২, ৮, ৪ | Ge → 0.3V (32) ২, ৮, ১৪, ৪ |
|------------------------------|----------------------------------|

I-v characteristic curve:

Question Answer



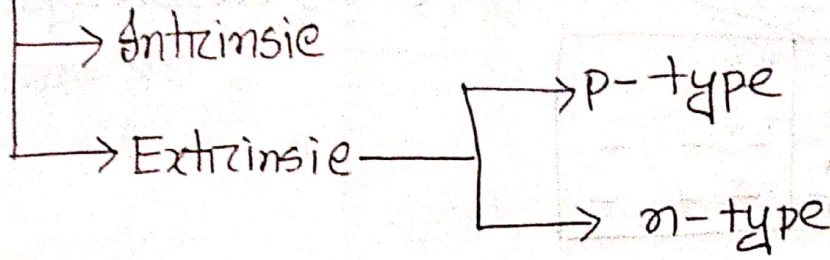
Ge use क्या सुविधाजनक नाकि ?

* निडर्रियास लेके last orbite हर दूरत अनेक बेझि electron को realize करा थाय इहज एवतु temperature बाडले एदेर characteristic change इरय थाबे एवतु unstable इरय थाय, तार्इ Ge अ्यहार क्या सुविधाजनक ना,

Si हर लेखने

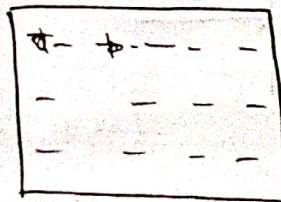
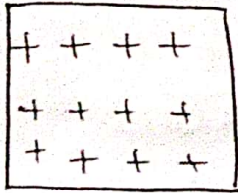
⊕ → distance कम तार्इ temperature बाडले एर characteristic change इरय ना तार्इ Si अ्यहार क्या सुविधाजनक electron realize करा इरय ना इहजे

Semi conductor:



Doping: → বাহ্যিক ভাবে জেটাল add করলে conductivity বাড়াবার জন্য Doping ব্যবহার করা হয়।

→ electron এর অভাব বাড়াতে মাঝ।



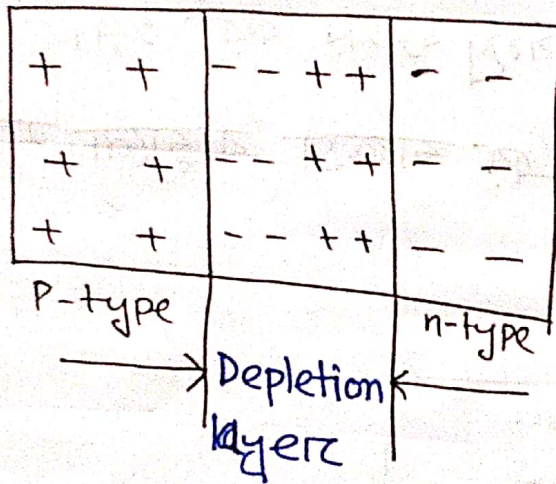
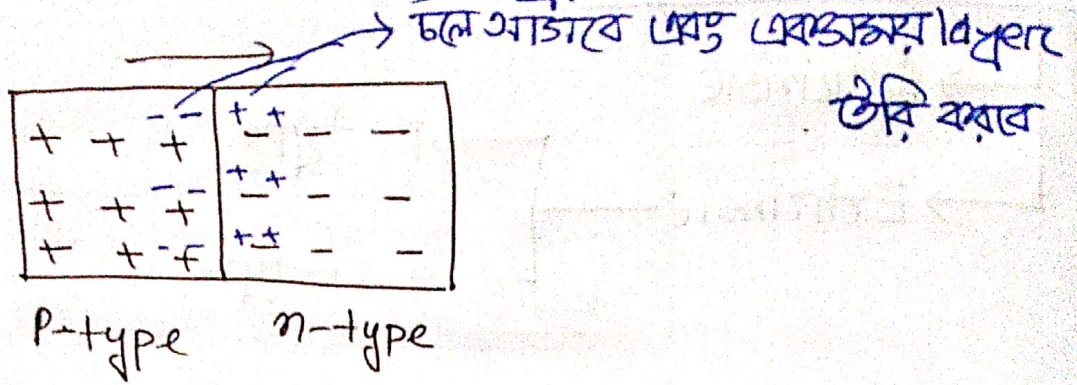
hole ← p-type

n-type →

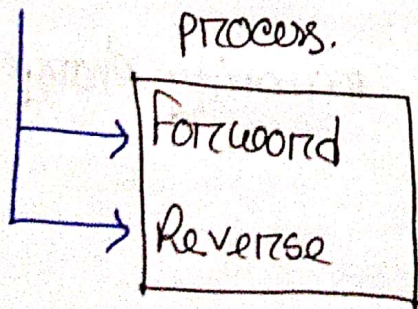
majority charge carrier → e h

minority charge carrier

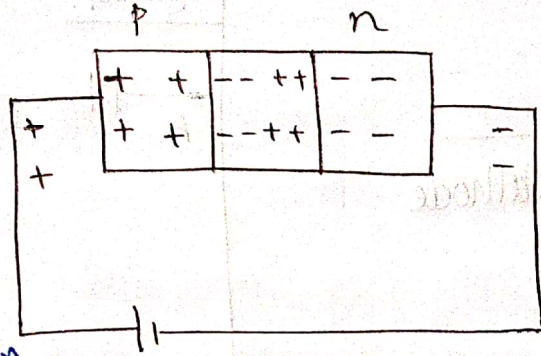
□ connect કરાવેલ → (p+n) type



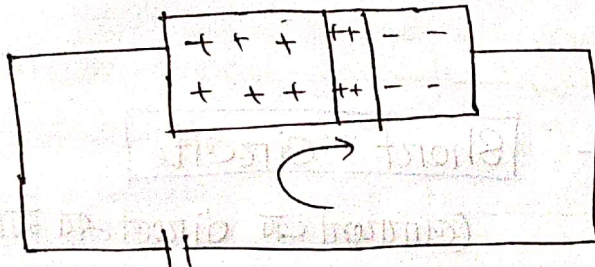
□ Biasing: વાહકોના પ્રવાહને અસર કરવા માટેના વોલ્ટેજ પ્રક્રિયા.



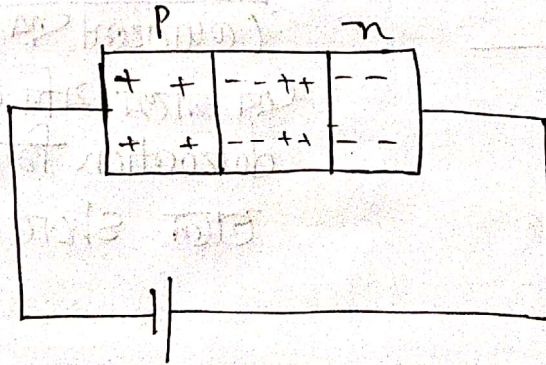
Forward:



→ বিপরীত দিকী চার্জ পরস্পরকে আকর্ষণ করে depletion layer গঠন করে হয় যার → current follow হয়। অর্থাৎ,



Reverse:

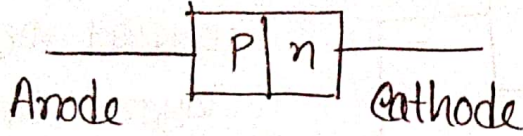


* P-type এর (+) এর সাথে বোম্ব (-) প্রান্ত এবং n-type এর (-) এর সাথে বোম্ব (+) প্রান্ত যুক্ত হলে reverse biasing তৈরি হয়।

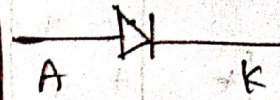
* resistivity তুলি মানে current বহন follo করে (leakage current)

Question:
P-n type যুক্ত
add করা হয়
Forward এবং Reverse
Biasing এর condition
কিভাবে হয়??

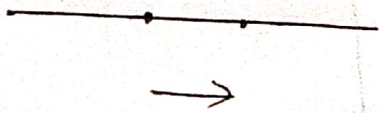
Diode:



Symbol:



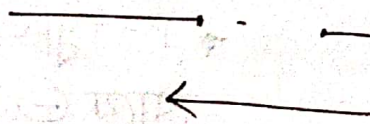
FB:



Short circuit

(Current flow direction same as diode direction detection will be done or short circuit)

R.B:



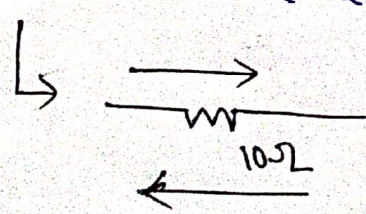
Open circuit

(Current flow direction opposite to diode direction detection will not be done or short circuit)

Q. Difference between Unilateral element and Bilateral element?

Unilateral element:
Diode resistance

Bilateral element: → Current same in both direction element change 2x or more.

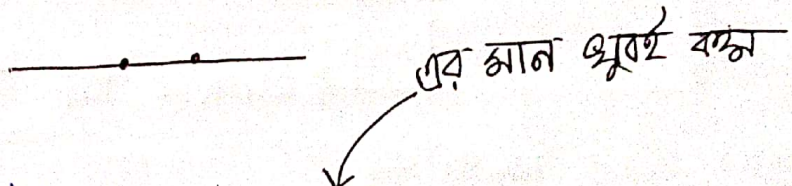


passive te element:

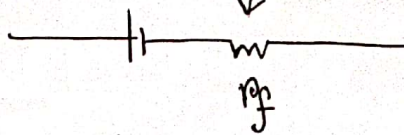
| USE | USE |
|------|------|
| Si | Ge |
| 0.7V | 0.3V |

Diode ki model:

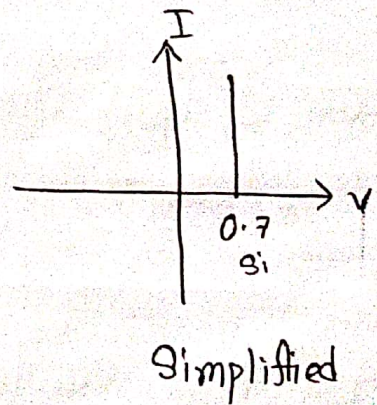
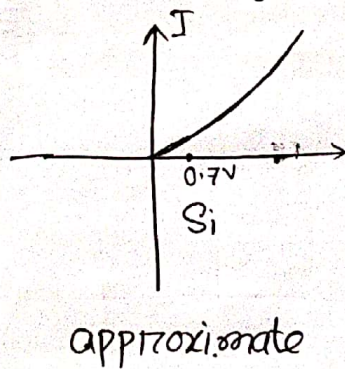
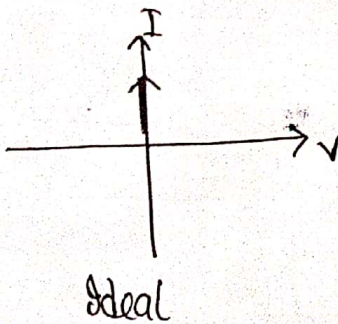
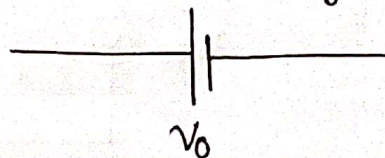
(i) Ideal model:



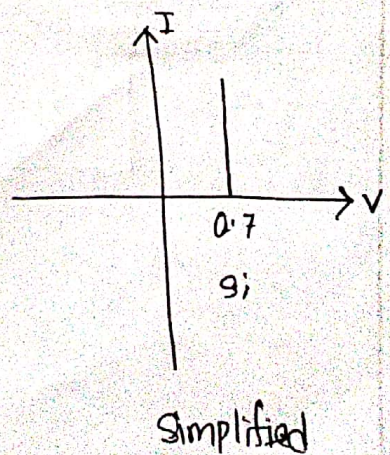
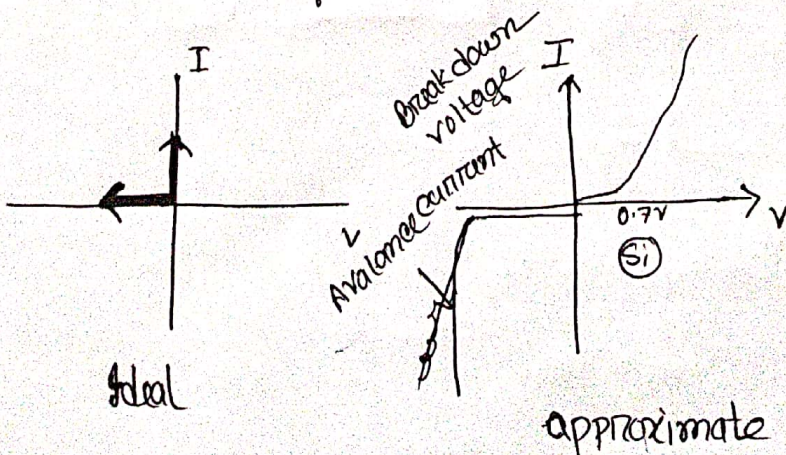
(ii) Approximate modal:



(iii) Simplified modal:



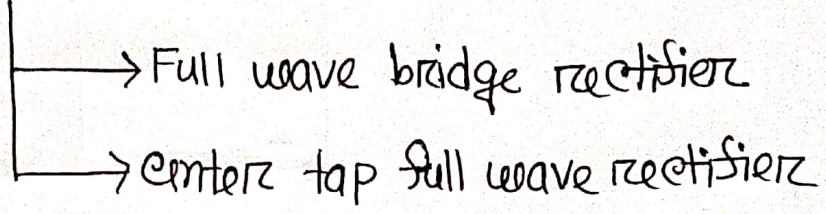
reverse Biases ki :



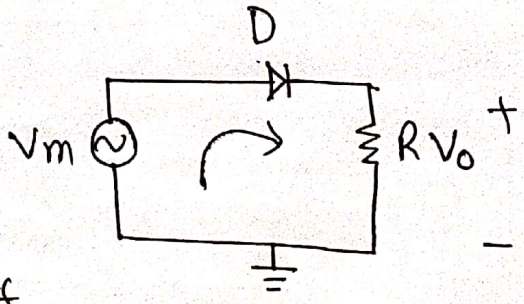
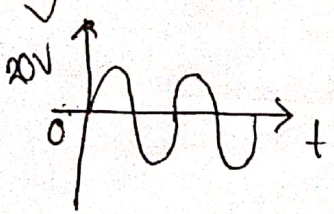
Rectifier: এমন Device যা AC \rightarrow DC করে

2 types:

- ① Half wave rectifier
- ② full wave " " "



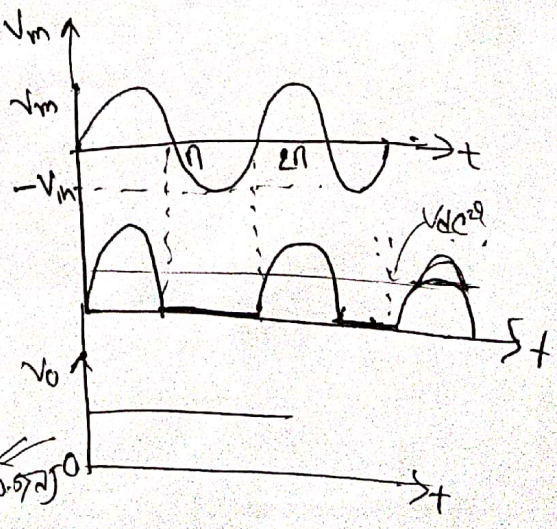
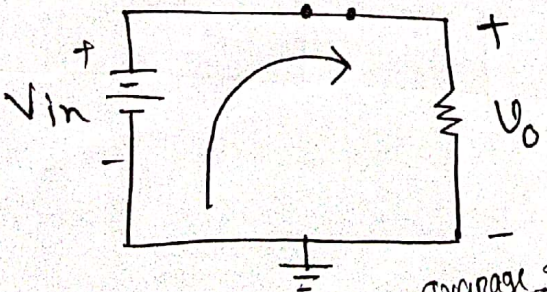
Half wave rectifier:



যদি 1 Half circle off

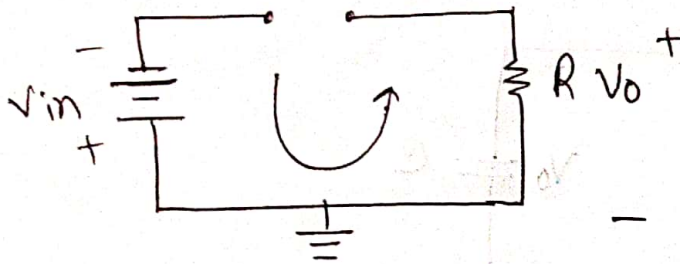
এবং পরে " " " " On থাকে,

for half circle,

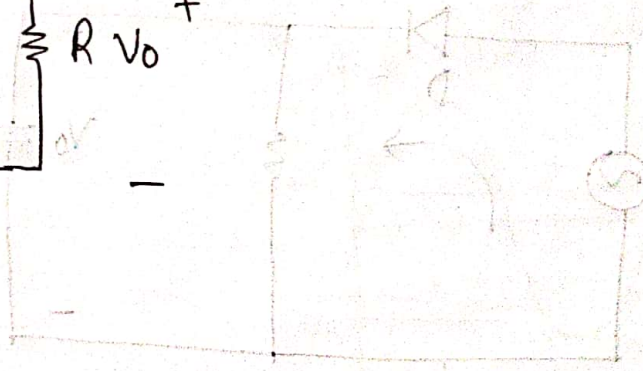


average \rightarrow $-V_m + V_0 = 0$
 $\therefore V_m = V_{in}$

For negative half circle,



$$V_o = IR = 0 \times R = 0V$$



Q. Explain the half wave rectifier?

□ Ripple: AC ও DC শরীর বৈশিষ্ট্য প্রাপ্ত

$$V_{dc} = \frac{1}{2\pi} \int_0^{\pi} v_m \sin t \, dt$$

$$= \frac{1}{2\pi} v_m [-\cos t]_0^{\pi}$$

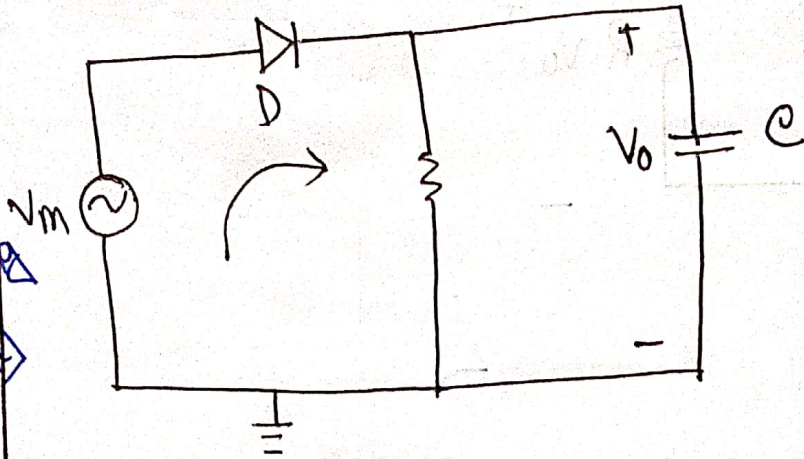
$$= \frac{v_m}{2\pi} (-\cos \pi + \cos 0)$$

$$= \frac{v_m}{2\pi} \times 2 = \frac{v_m}{\pi} = 0.318 v_m$$

$$\boxed{V_{dc} = 0.318 v_m} \rightarrow \boxed{\text{Average value}}$$

For pure dc:

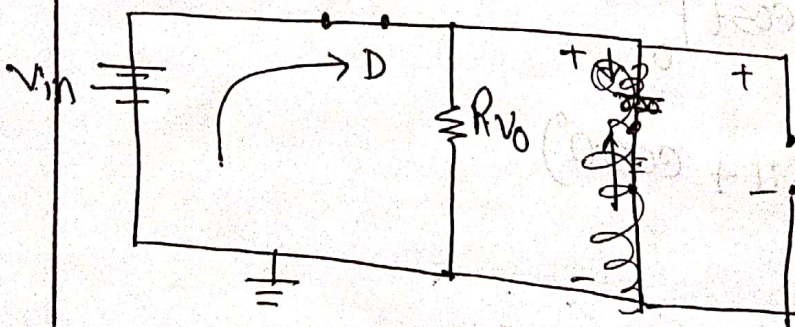
[dc blocking capacitor]



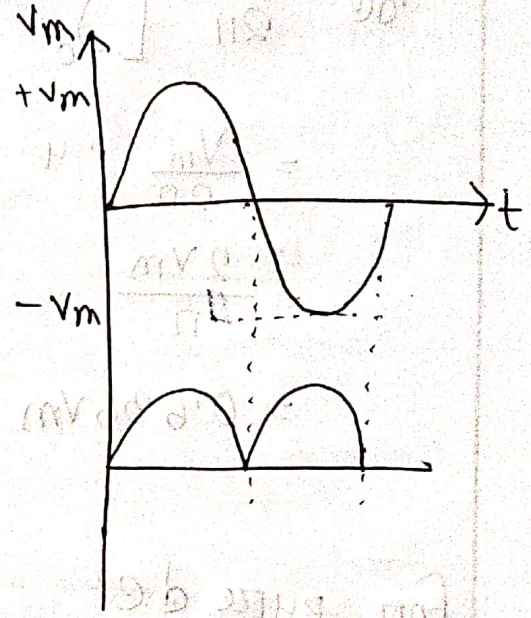
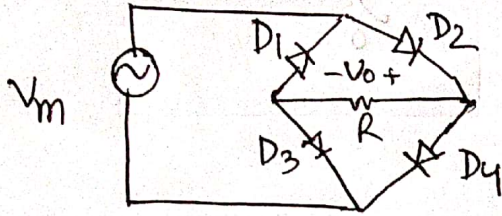
$$X_C = \frac{1}{2\pi f C}$$

$$f \rightarrow 0 \Rightarrow C \rightarrow \infty$$

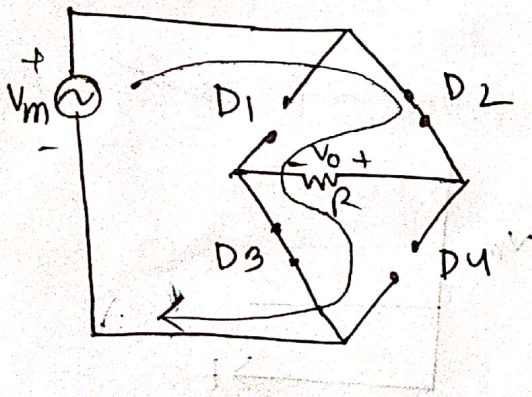
$$f \rightarrow \text{high} \Rightarrow C \rightarrow 0$$



Full wave rectifier: Both half cycle এ conduction করে



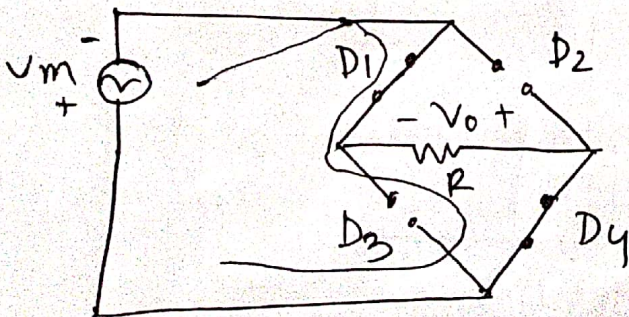
for positive half cycle,



$$-V_{in} + V_o = 0$$

$$\Rightarrow V_o = V_{in}$$

for negative half cycle;



$$-V_{in} + V_o = 0$$

$$\Rightarrow V_o = V_{in}$$

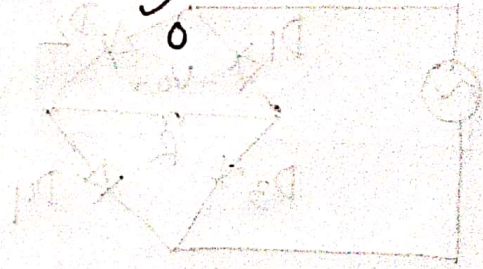
Average value

$$V_{dc} = \frac{1}{2\pi} \left[\int_0^{\pi} V_m \sin t dt + \int_{\pi}^{2\pi} V_m \sin t dt \right]$$

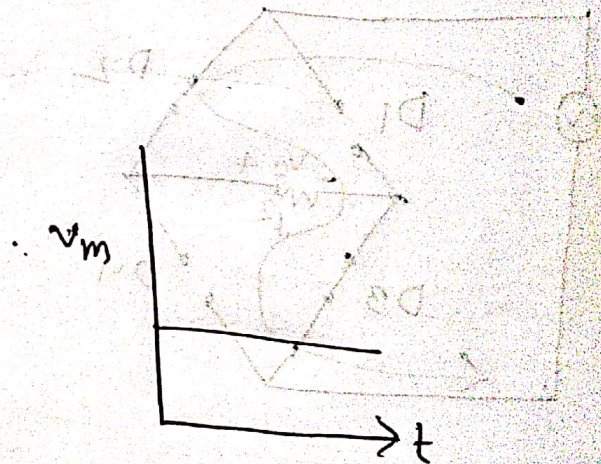
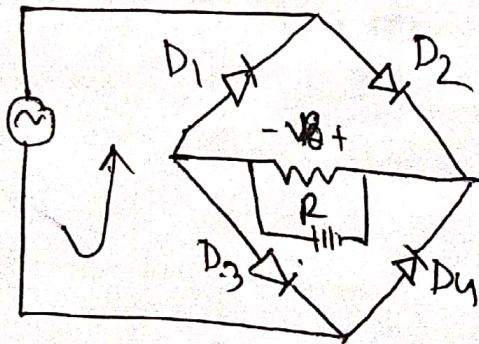
$$= \frac{V_m}{2\pi} \cdot 4$$

$$= \frac{2V_m}{\pi}$$

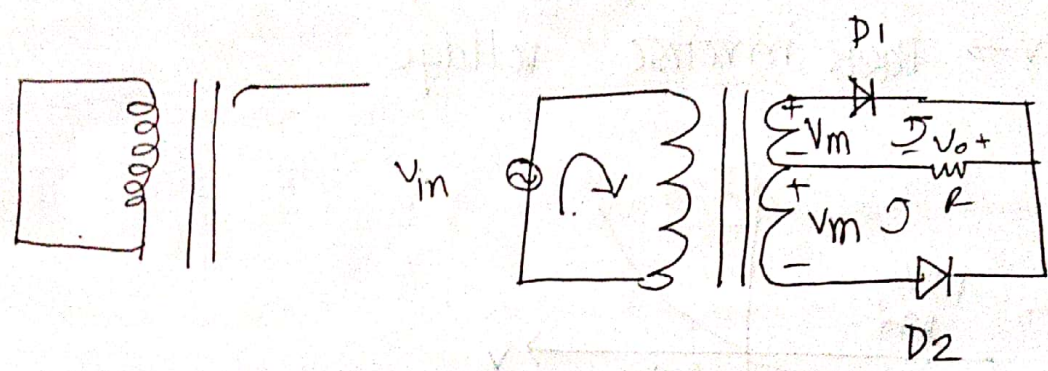
$$= 0.636 V_m$$



For pure dc:



Full wave rectifier using center tap transformation:



Step down transformer use 230/24V

$$\boxed{230/24V}$$

Input wave transformation

For positive half cycle:

D_1 on, D_2 off

$$-V_{in} + V_0 = 0$$

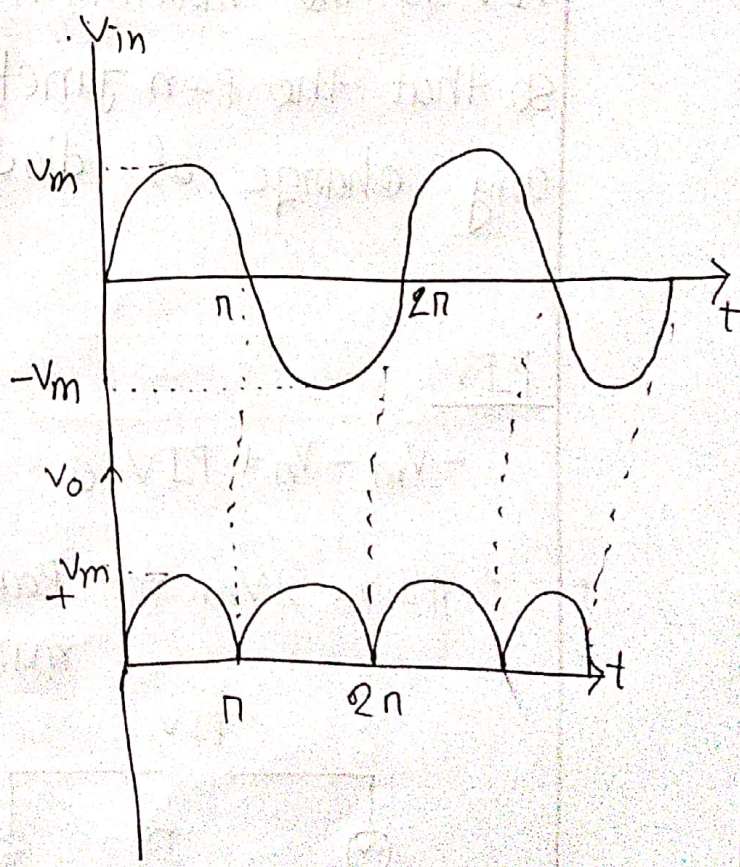
$$\therefore V_0 = V_{in}$$

For negative half cycle:

FD $\rightarrow D_2$ on, D_1 off

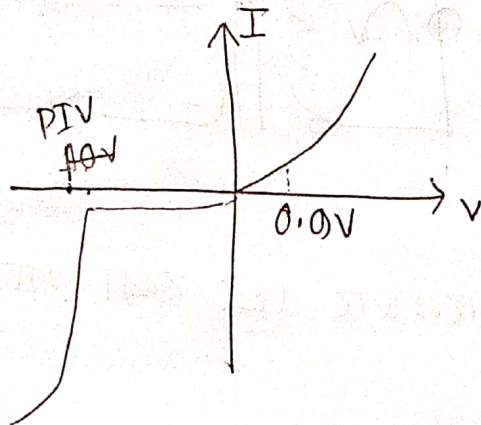
$$-V_{in} + V_0 = 0$$

$$\therefore V_0 = V_{in}$$



PRV → Peak reverse voltage

PIV → Peak inverse voltage

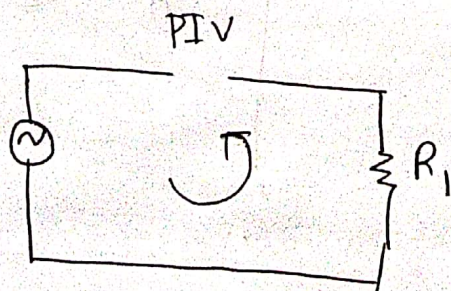


PIV is the maximum reverse Biasse potential so that the P-n junction with stands without any change of diode.

PIV:

$$-V_m - V_n + PIV = 0$$

⇒ $PIV = 2V_m$. ← Peak voltage का 2 गुना फिर maximum 2/25.



$$-V_m - 0 + PIV = 0$$

$$\Rightarrow \boxed{PIV \geq V_m}$$

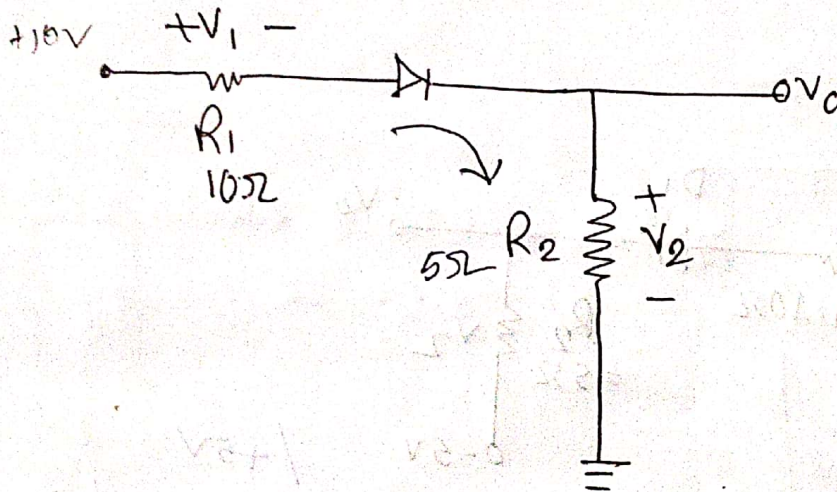
Half bridge wave

bridge

- (i) PIV 2 গুণন করতে হবে } Half wave
 (ii) center define করা করতে হবে } Half wave

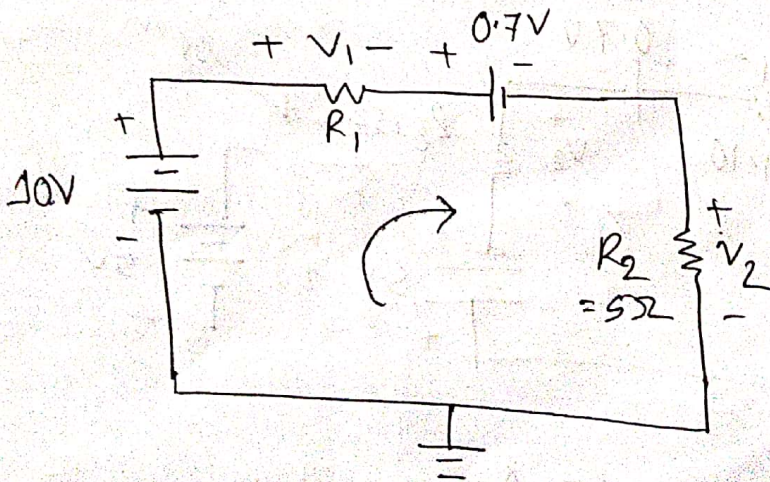
যদি Half wave avoid করা Full wave use করা হয়।

Math:



$$V_1, V_2, V_0, I = ??$$

Ans:



Applying KVL

$$-10 + I \times 10 + 0.7 + 5I = 0$$

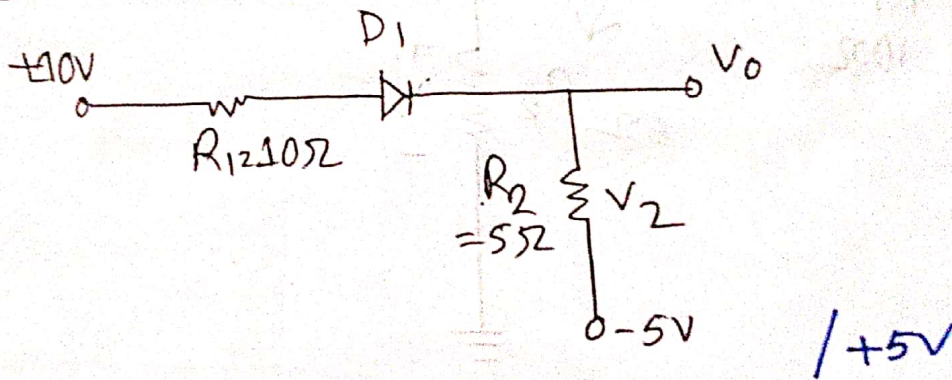
$$\therefore I = \frac{10 - 0.57}{10 + 5}$$

$$V_1 = I \times 10 = \boxed{} \text{ V}$$

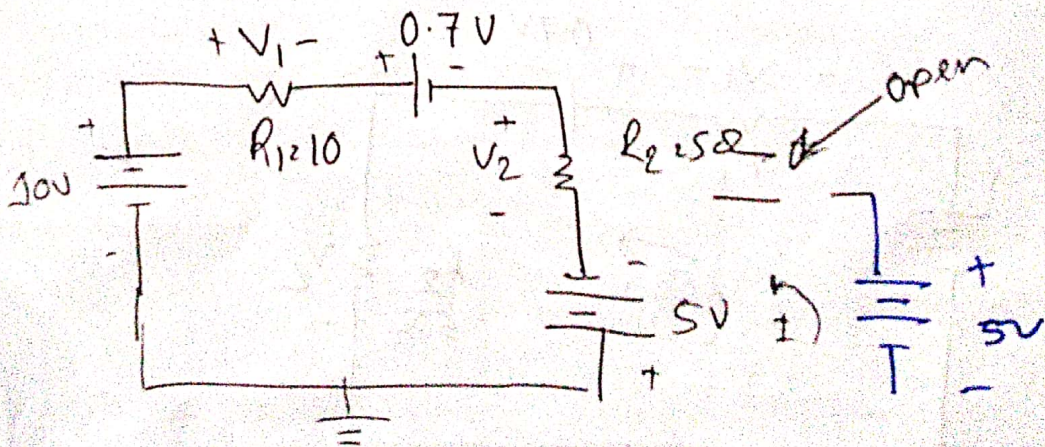
$$V_2 = I \times 5 = \boxed{} \text{ V}$$

$$V_0 = V_2$$

OR:



$$V_1, V_2, V_0 \Rightarrow I = ?$$



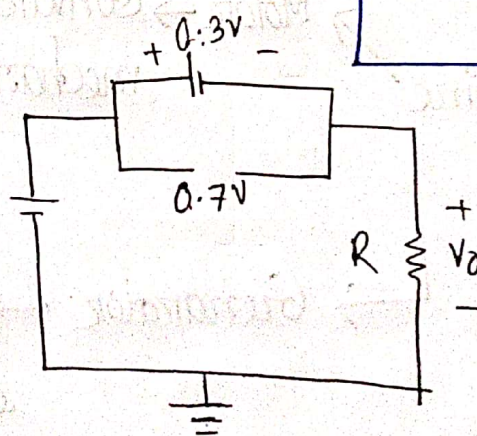
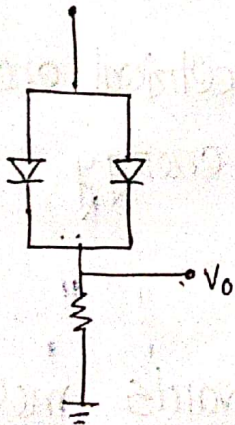
$$-10 + 10I + 0.7 + 5I - 5 = 0$$

$$\Rightarrow I = ?$$

$$-V_0 + V_2 - 5 = 0$$

$$\Rightarrow V_0 = V_2 - 5$$

$$\Rightarrow V_0 = \square$$



Asserment
 → for CT 4

Problem no:
 Ex: 2.5, 2.7, 2.6, 2.7, 2.9,
 2.10, 2.12, 2.14, 2.17

□ $V =$ দেয়া

$I = n$

৭টি বাল্ব ১সঙ্গে connect করলে @ (size) কে কত I

প্রবাহিত হবে ৭

New chapter

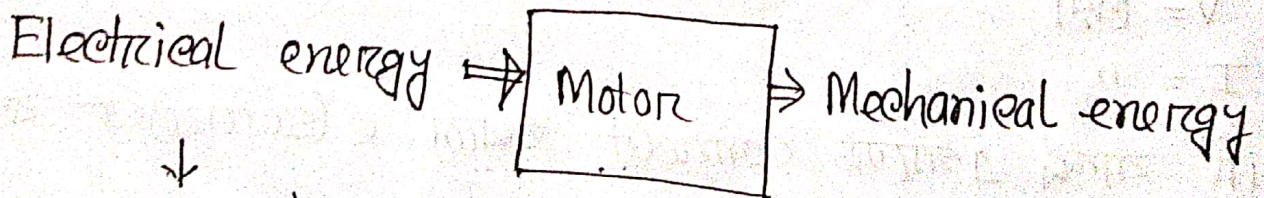
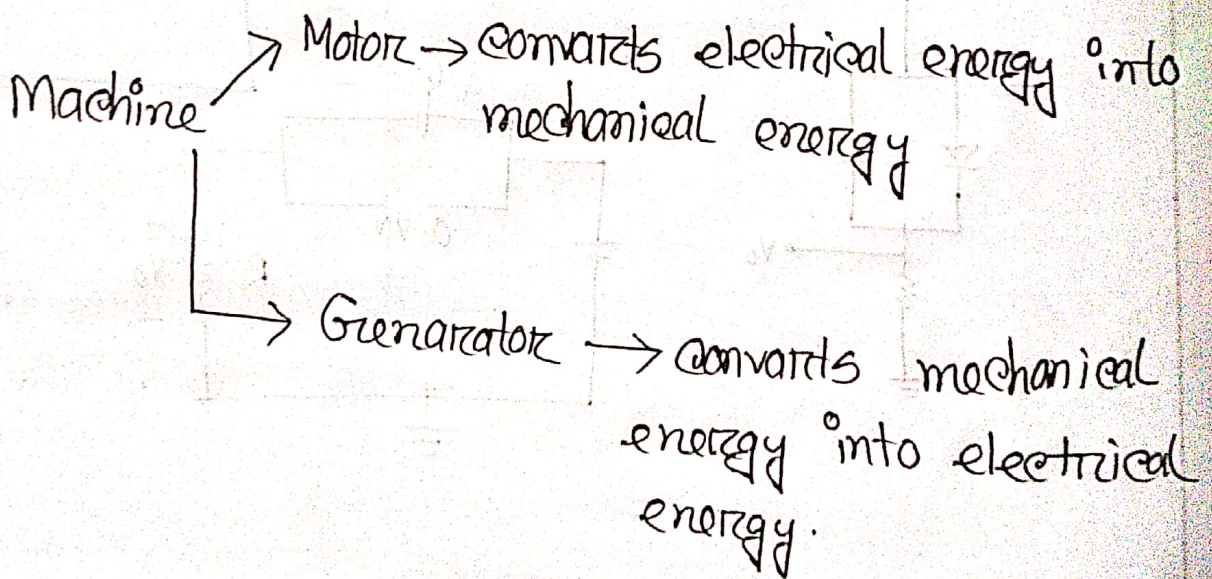
Machine

Machine \rightarrow Electrical energy to mechanical energy to convert করে

2 types:

\rightarrow Motor

\rightarrow Generator



↓
Example
(power point)

input electrical energy থাকলে motor
" " mechanical " " Generator

□ DC Generator হতে শেখ গতি condition maintain করতে হয়।

□ DC Generator: → গতি condition:

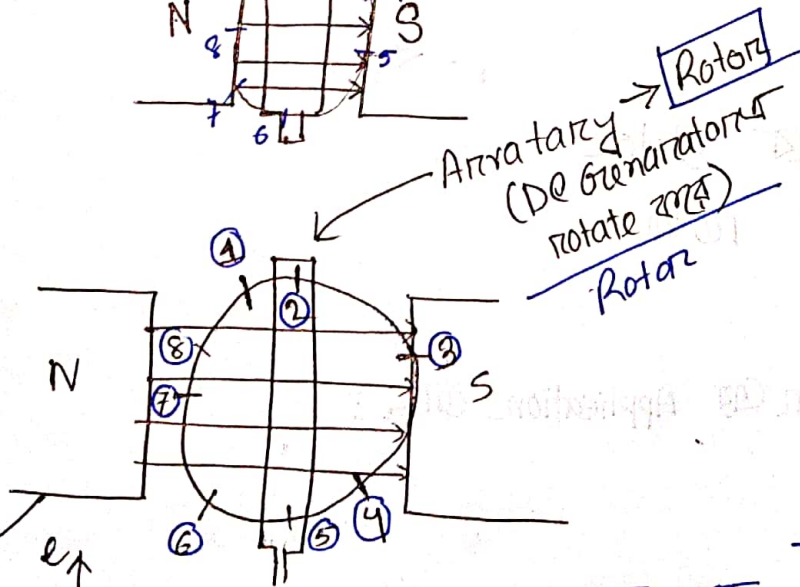
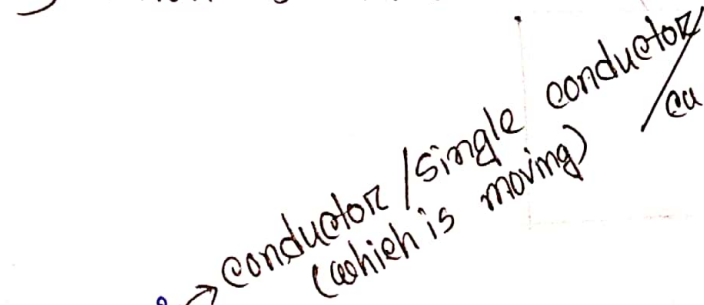
- i) Magnetic field
- ii) A group of conductor
- iii) Motion of that conductor.

↓ গতি important

(Moving condition / vibration / গতিশীলতা)

Induce voltage এর পরিমাণ alternative voltage

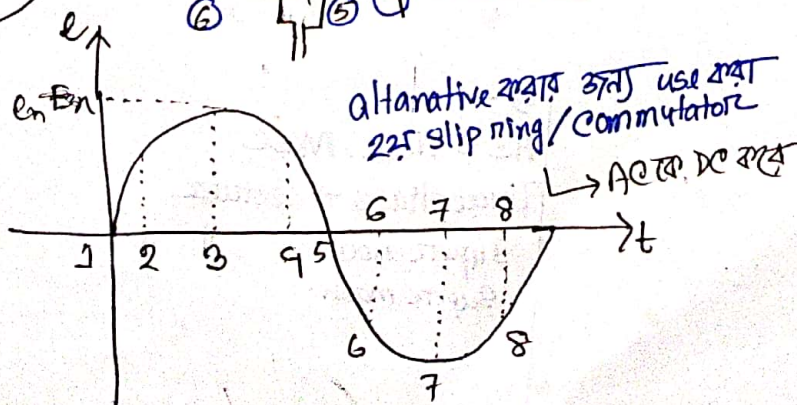
□



কোনো magnetic conductor দিলে
এ conductor এর,
Motion এর কারণে electric
flux কাজ করবে এবং
যে পরিমাণ flux কাজ
করবে সে পরিমাণ voltage
কাজ করবে

→ ব্যাবহারের Law
(electric magnetic
Law)

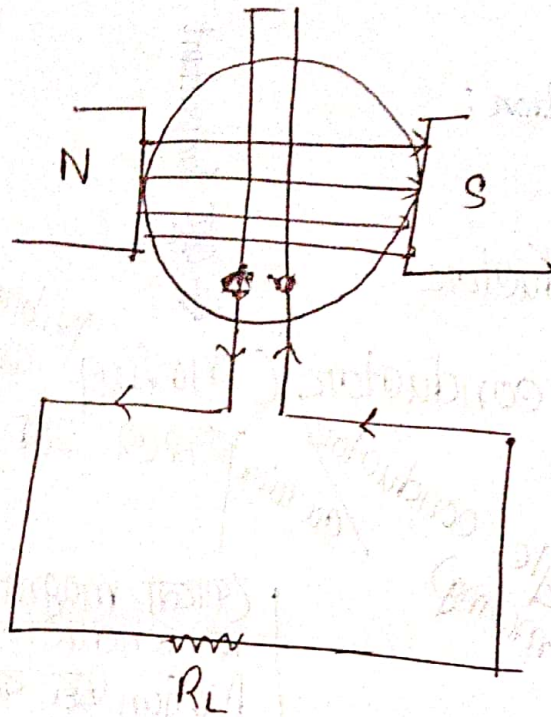
Field System
Generator



9. DC Generator এর principle?

conductor parallel এর move
করলে এর induce voltage 0
এ R angle করলে induce voltage
করবে

☐ Generator:



☐ Alternator:

Field station ২৫ stator

Armature ২৫ rotor

১. Generator ও Motor এর Application লেখা ?

- ১ →
- Ac → Node, Mase
- Threephase → Lecturer
- Super node
- Super mash.